



## Capability evaluation of deep learning for time-series prediction in medical packaging production

Diploma Thesis for obtaining the academic degree **Master of Science** as part of the study **Biomedical Engineering** 

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#### Abstract

With the increasing production volatility in the power grids due to renewable energy sources, an exact and individualized energy demand forecast of industrial customers is becoming more important to ensure the supply-demand balance at any time. In this thesis three commonly used deep learning algorithms, Artificial Neural Networks (ANNs), Convolution Neural Networks (CNNs) and Long-Short Term Memory Networks (LSTMs) are tested for their ability to predict the load demand of three industrial data sets one day in advance with an accuracy of 15 minutes. The results were compared to each other and to the method currently used by the industrial partners. It was found that deep learning algorithms can improve the prediction accuracy by 20% - 45% compared to the currently used method. Among the Deep Learning algorithms, LSTM achieved the best results, but only by 2% - 5% compared to the second-ranked algorithm, with a much higher training effort. Therefore, LSTM models generally are to be prefered over ANN or CNN algorithms. However, in cases requiring frequent retraining, using a second-ranked ANN or CNN algorithm may be advisable, as they are faster in training.

#### Kurzfassung

Der steigende Anteil erneuerbar Energieträger führt zu Schwankungen in der Stromproduktion und reduziert damit aufgrund erhöhter Planungsunsicherheit die Netzstabilität. Um das Stromangebot und die Stromnachfrage im Gleichgewicht und somit die Netzstabilität zu gewährleisten, gewinnt eine genaue Bedarfsvorhersage zunehmend an Bedeutung. In dieser Arbeit werden Artificial Neural Networks (ANNs), Convolution Neural Networls (CNNs) und Long-Short Term Memory Networks (LSTMs), drei häufig verwendete Deep Learning Algorithmen, in ihrer Fähigkeit verglichen, den Strombedarf von drei Industriedatensets einen Tag vorab mit einer Genauigkeit von 15 Minuten vorherzusagen. Die Ergebnisse der Algorithmen wurden zueinander sowie mit der, von den Industriepartnern, aktuell verwendeten Methode verglichen. Die Deep Learning Algorithmen konnten, verglichen mit der aktuell verwendeten Methode, die Vorhersagegenauigkeit um 20% - 45% verbessern. Dabei erzielten die LSTM Modelle die besten Ergebnisse, allerdings nur um 2% - 5%, verglichen mit dem jeweils zweitbesten Algorithmus. Damit sind LSTM Modelle gegenüber ANN oder CNN Modellen grundsätzlich zu bevorzugen. Da allerdings LSTM Modelle wesentlich aufwendiger zu trainieren sind, kann es bei Problemstellungen, in denen häufiges neu-trainieren notwendig ist, vorteilhaft sein, ein zweitplatziertes ANN oder CNN Modell zu wählen.

Ich nehme zur Kenntnis, dass ich zur Drucklegung meiner Arbeit unter der Bezeichnung

## Diplomarbeit

nur mit Bewilligung der Prüfungskomission berechtigt bin.

### Eidesstattliche Erkärung

Ich erkläre an Eides statt, dass die vorliegende Arbeit nach den anerkannten Grundsätzen für wissenschaftliche Abhandlungen von mir selbständig erstellt wurde. Alle verwendeten Hilfsmittel, insbesondere die zugrunde gelegte Literatur, sind in dieser Arbeit genannt und aufgelistet. Die aus den Quellen wörtlich entnommenen Stellen, sind als solche kenntlich gemacht.

Das Thema dieser Arbeit wurde von mir bisher weder im In- noch Ausland einer Beurteilerin/einem Beurteiler zur Begutachtung in irgendeiner Form als Prüfungsarbeit vorgelegt. Diese Arbeit stimmt mit der von den Begutachterinnen/Begutachtern beurteilen Arbeit überein.

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Valentin Frossard

# Table of Abbreviations

AR	Autoregressive Models
ARIMA	Autoregressive Integrated Moving Average
ARMA	Autoregressive Moving Average
BPTT	Backpropagation-Through-Time
CAE	Cumulative Absolute Error
CEC	Constant Error Carousel
CNN	Convolution Neural Network
ESM	Seasonal Exponential Smoothing Method
LSTM	Long Short-Term Memory
MA	Moving-Average Models
MAE	Mean Absolute Error
MLP	Multilayer Perceptron
MSE	Mean Square Error
NN	Neural Network
RMSE	Root Mean Square Error
RNN	Recurrent Neural Network
TF	Transfer Function

#### Preamble

This work was carried out as part of the master's programme in Biomedical Engineering. Due to data availability, deep learning algorithms for time series prediction were compared using power consumption data. Nevertheless, the gained knowledge is relevant for the biomedical engineering field and can be applied to biomedical engineering problems. For example, the algorithms can assist to make the health care system more efficient or to ease everyday life for patients with chronic diseases.

Recently, a variety of problem settings in health care have been approached using deep learning for time-series prediction. Masum et al. (Masum et al. 2019) applied LSTM, Bi-LSTM and CNN deep learning algorithms to forecast blood pressure 30 minutes in advance, aiming to detect critical conditions early. Similarly, Zhu et al. (Zhu et al. 2020) utilizes recurring neural networks to predict the upcoming glucose levels of Type I Diabetes patients 30 minutes ahead, to improve insulin application planning.

Shih and Rajendran (*Shih et al. 2019*) tested the performance of classical statistical methods (ARMA, ARIMA, ESM) and machine learning algorithms (ANN, multiple regression) predicting the blood supply in Taiwan to minimize outdating and shortage of stored blood.

Lastly, Kaushik et al. (Kaushik et al. 2020) predicted the average expenditures on pain medication using ARIMA, MLP and LSTM for supply demand planning.

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## 1 Introduction

### 1.1 Introduction Electricity Markets

Since electricity cannot be stored easily, the amount of electric energy introduced into the electric grid must be equal the amount of electric energy consumed. To achieve equilibrium, producers and consumers are organized in balance groups and each group is liable to balance energy consumption and production within. This can be achieved by either adjusting demand and supply within the group or by purchasing and selling energy on the electricity spot markets.

Balance groups are geographically bundled and overseen by a control area manager ("Bilanzgruppenführer"). In case of a demand-supply-mismatch due to inaccurate demand prediction, power plant failures or availability changes of renewables, the control area manager restores equilibrium by utilizing primary (< 30 sec), secondary (< 15 min) or tertiary spinning reserve, consuming balancing energy. The balancing energy is provided by specialized, quick-reaction electric energy sources. Costs for the balance energy can be a multitude of the normal electricity rates and are charged to the balance group responsible for the mismatch. (APG 2020)

## 1.2 Forecasting Motivation

The global electric energy demand is increasing exponentially and expected to continue growing. As electric energy cannot be stored, the electric energy production and demand need to be in equilibrium. If the equilibrium is distorted, the network frequency raises with a surplus of energy or falls with energy shortage. Heavy distortions can cause equipment damage or even blackouts and must be avoided at all costs. Precise demand prediction enables power suppliers to plan for the future demand and match the production accordingly.

Inaccuracies in demand prediction can result in two major problems. First, an over-estimation will cause power suppliers to schedule higher capacities, unnecessary spinning reserve and will ultimately lead to a waste of energy resources and distribution inefficiencies (*Hong 2009*). Second, an under-estimation of load prohibits providing sufficient load capacities, spinning reserve and causes high costs in the peaking unit, discouraging any economic and industrial development (*Hong 2009*).

The European electricity consumption splits into three major segments: "households", "commercial & public service" and "industry", shown in *Figure 1.2.* Each segment represents approximately one-third of the consumption, with "industry" being the largest (*Agency 2020*). With the rise of building automation and the wide adaption of smart meters, demand prediction for homes, office buildings and entire districts have been covered extensively by the scientific community (*Wei et al. 2018; Chen et al. 2017; Valgaev et al. 2017*). However, the industrial sector has received limited attention. The reasons can only be assumed, but are most likely to be found in the lack of publicly available data. By partnering with *Campfire Solutions*, a startup at the *TUW i*<sup>2</sup>*ncubator*, the author was able to obtain three extensive industrial electric power consumption datasets, that will be introduced in Section 4.2



Figure 1: European Electricity Consumption by Consumer Type (Agency 2020)

### 1.3 Time Series Prediction

Electricity demand data is time series data, with a energy consumption measurement for every quarter-hour. Predicting future energy demand is a time-series prediction problem. Time series predictions usually aim to forecast a value at some future point in time t + t' using available observations of a time series up to time t. Time series prediction problems can take various forms and are grouped according to the following categories. (Han et al. 2019)

#### 1.3.1 Time Intervals of Observations

The majority of existing studies presume equidistant intervals of time for the data at hand. This condition simplifies data handling and the problem can be formulated as *(Han et al. 2019)* 

$$\hat{x}_{t+h} = f(x_t, x_{t-1}, \dots, x_{t-N}) \tag{1}$$

with  $\hat{x}_{t+h}$  being the predicted result,  $x_t, x_{t-1}, ..., x_{t-N}$  referring to the sequence the prediction is based upon and N being the number of inputs. h can be 1 (C.-H. Lee et al. 2014, Miranian et al. 2013) for one-step ahead predictions or, for multi-step predictions, any positive integer (Taieb et al. 2012, Parlos et al. 2000, Han et al. 2019).

In some cases equidistant time intervals cannot be assumed (*Ramasso et al. 2012*, Aladag et al. 2012) and the problem of time series prediction has to be extended by  $l_1, l_2, ..., l_N$ , representing the various time spaces (*Han et al. 2019*)

$$\hat{x}_{t+h} = f(x_{t-l_1}, x_{t-l_2}, \dots, x_{t-l_N}, l_1, l_2, \dots, l_N)$$
<sup>(2)</sup>

#### 1.3.2 Prediction Strategy

To predict several time steps ahead, either a recursive or a direct prediction strategy can be deployed. The recursive prediction strategy is an iterative process (Young

2012, Mirikitani et al. 2010, H. Liu et al. 2012), using subsequent predicted values to predict the next and can be expressed as follows (Han et al. 2019)

$$\hat{x}_{t+1} = f(x_t, x_{t-1}, \dots, x_{t-N})$$

$$\hat{x}_{t+2} = f(\hat{x}_{t+1}, x_t, \dots, x_{t-N+1})$$

$$\dots$$

$$\hat{x}_{t+M} = f(\hat{x}_{t+M-1}, \hat{x}_{t+M-2}, \dots, x_{t-N+M})$$
(3)

with M being the number of values to be predicted,  $\hat{x}_t$  a predicted value,  $x_t$  a measured value and N the number of values used for one prediction. The disadvantage of the recursive prediction is the accumulation of prediction error and thereby the gradual deterioration of prediction accuracy.

For this reason some researchers (*Zhao et al. 2015, Han et al. 2016*) focus on predicting multiple data points at once. This direct prediction strategy can be expressed as (*Han et al. 2019*)

$$\hat{\mathbf{X}} = f(x_t, x_{t-1}, ..., x_{t-N})$$
(4)

with  $\hat{\mathbf{X}} = [\hat{x}_{t+1}, \hat{x}_{t+2}, ..., \hat{x}_{t+M}]^T$  being the predicted vector.

#### 1.3.3 Univariate and Multivariate Modelling

â

A model with solely one input variable is a univariate model (*Pankratz 2009*) and with more than one input variable it is a multivariate model (*Khashei et al. 2011*). Univariate models are defined according to *Equation 1* and multivariate models are defined as (*Han et al. 2019*)

$$\hat{x}_{t+1} = f(x_t^1, \dots, x_{t-N}^1, x_t^2, \dots, x_{t-N}^2, \dots, x_t^L, \dots, x_{t-N}^L)$$
(5)

with L representing the number of input variables.

### 1.4 Research Question and Objectives

The main research question is, which standard deep learning algorithm is best suited for day-ahead electric load forecasting in 15 minute accuracy for industrial production data?

The following objectives should be accomplished during this master thesis:

- 1. Obtain three industrial production datasets covering a minimum of 1.5 years
- 2. Select three standard deep learning algorithms to test
- 3. Construct a real-life baseline approach
- 4. Build a machine learning pipeline to pre-process data, train models and automatically perform hyper-parameter tuning
- 5. Select and suggest the model exhibiting the smallest error

## 2 State of the art

Electricity demand prediction models are classified by type, as introduced in *Section* 2.1, or the predicted time horizon. Models can be built to create short-term, medium-term and long-term forecasts (*Suganthi et al. 2012*). Short-term forecasts targets time spans of hours to weeks, mid-term forecasting covers a duration of weeks to a year and long-term forecasts cover anything beyond (*Suganthi et al. 2012*).

## 2.1 Model Types

Prediction problems can be solved by utilizing white-box, black-box or grey-box approaches. White-box models rely on a deep understanding and mathematically modelling of underlying physical or chemical processes and their boundary conditions for both, building operations and production activities (*Ferrarini et al. 2019*). Using white-box models, a forecast can be created by solving the modelled set of equations for every point in time. White-box models provide good interpretability, however the model creation requires in-depth process knowledge, is labour intensive and solely applicable to the process the model was created for. Ferrarini et al. (*Ferrarini et al. 2019*) applied white-box modeling to create an energy model of a multi-storey residential building and Vaccaro et al. (*Vaccaro et al. 2012*) used a white-box model as a baseline in wind intensity predictions.



Figure 2: Black-Box concept inspired by (Bunge 1963)

Contrary, a black-box model is a purely data-driven approach. The system is viewed as unknown entity and its properties are derived ("learned") from the relationship between input and output variables (*Bunge 1963*), as shown in *Figure 2*. Black-box models do not require system specific expert knowledge and algorithms can be easily applied to multiple problem settings of the same kind. On the down-side, black-box models lack transparency and interpretability of derived predictions, not being able to explain why a specific decision has been made (*Holzinger et al. 2017*). Deep learning algorithms are black-box models, since their high level of recursiveness limits interpretability (*Rudin 2019*).

A hybrid form between white-box and black-box models can be classified as greybox models. Grey-box models have been applied for energy demand prediction in office and residential buildings (*Berthou et al. 2014, Li et al. 2016, Afram et al. 2018*) and to predict output power of both, photovoltaic (*Paulescu et al. 2017*) and wind power plants (*Ferrarini et al. 2019*).

## 2.2 Short-term load forecasting using statistical methods

In the field of short-term load forecasting, any type of timeseries forecasting technology being en-vogue at that time, has been applied, aiming to improve prediction performance. Historically Box and Jenkins models have shown to be well-suited in forecasting short term loads (*Hagan et al. 1987*), which have then been surpassed by ARIMA models (*Amjady 2001*)

Historically, many different statistical methods have been deployed in the field of short-term load forecasting. Moghram and Rahman (*Moghram et al. 1989*) compared the performance of multiple linear regression, stochastic time series, general exponential smoothing, state space method and a knowledge-based approach, which can be considered traditional statistical forecasting methods.

#### 2.2.1 Multiple Linear Regression

In the multiple linear regression model, the load is calculated by inferring from explanatory variables and the model is expressed according to Moghram and Rahman (Moghram et al. 1989) as

$$y(t) = a_0 + a_1 x_1(t) + \dots + a_n x_n(t) + a(t)$$
(6)

y(t) electrical load

 $x_n(t)$  explanatory variable correlated with y(t)

a(t) random variable with zero mean and constant variance

 $a_n$  regression coefficients

These explanatory variables are identified by performing a correlation analysis between the independent variables and the load. The regression coefficients, used to calculate the prediction, are determined using the least square estimation technique. To determine the significance of the regression coefficients, statistical tests, for example the F-Test, are performed. (Moghram et al. 1989)

#### 2.2.2 Stochastic Time Series

Stochastic time series modelling infers the prediction as output of a linear filter with random series input, zero mean and unknown fixed variance. Depending on the filter used, Autoregressive Models (AR), Moving-Average Models (MA), Autoregressive Moving-Average Models (ARMA), Autoregressive Integrated Moving Average Models (ARIMA), Seasonal Models, as an extension to AR, MA, ARMA or ARIMA, or Transfer Function (TF) Models can be built (*Moghram et al. 1989*).

#### 2.2.2.1 Autoregressive Models (AR)

In the autoregressive model, the current values of y(t) is inferred linearly from its previous values y(t-1), ..., y(t-p) and a random noise a(t). The order p of the model depends on the temporal oldest value used to calculate the predicted value. The AR model can be written as *(Moghram et al. 1989)* 

$$y(t) = \Phi_1 y(t-1) + \Phi_2 y(t-2) + \dots + \Phi_p y(t-p) + a(t)$$
(7)

y(t)	electrical load
y(t-n)	historic values of y(t)
a(t)	random variable with zero mean and constant variance
$\Phi_n$	weight determining the importance of historic value, based on previous random noises

#### 2.2.2.2 Moving-Average Models (MA)

In the moving-average model, the current value y(t) of the time series, is inferred linearly from current and previous values of a white noise series a(t), ..., a(t-q). The noise series is calculated from the forecast errors between prediction and true value, once the true value becomes available. The order q of the model depends on the oldest considered value a(t-q) (Moghram et al. 1989). According to Moghram and Rahman (Moghram et al. 1989), the model can be written as

$$y(t) = a(t) - \Theta_1 a(t-1) - \Theta_2 a(t-2) - \dots - \Theta_q a(t-q)$$
(8)

y(t)	electrical load
a(t)	white noise
a(t-n)	previous values of white noise
$\Theta_n$	weighting factor

#### 2.2.2.3 Autoregressive Moving-Average Models (ARMA)

In the autoregressive moving-average model, the current value of the time series y(t), is inferred linearly from values of previous periods y(t-1), ..., y(t-p) as well as current and previous values of a white noise series a(t), ..., a(t-q). The order of the model depends on the oldest previous series value and oldest previous white noise value used (*Moghram et al. 1989*). According to Moghram and Rahman (*Moghram et al. 1989*), the model can be written as

$$y(t) = \Theta_1 y(t-1) + \dots + \Theta_p y(t-p) + a(t) + \Phi_1 a(t-1) + \dots + \Phi_q a(t-q)$$
(9)

y(t)	electrical load
y(t-n)	historic values of y(t)
a(t)	white noise
a(t-n)	previous values of white noise
$\Theta_n$	weighting factor for AR part
$\Phi_n$	weighting factor MA part

#### 2.2.2.4 Autoregressive Integrated Moving-Average Models (ARIMA)

The previously described models presume stationary processes, bearing that the mean and covariance among observations do not change with time. Having a non-stationary process, the observations first have to be transformed by differencing d times until the process becomes stationary. This is achieved by introducing the  $\nabla$  operator, with  $\nabla^d$ representing the  $d^{th}$  differentiation and  $\nabla^d y(t)$  the  $d^{th}$  derivative of ARIMA model y(t). To obtain the original time series y(t),  $\nabla^d y(t)$  hast to be integrated d times. (Moghram et al. 1989)

According to (Moghram et al. 1989), the differential model of the ARIMA can be written as

$$\Phi(B)\nabla^d y(t) = \Theta(B)a(t) \tag{10}$$

- y(t) electrical load
- a(t) white noise
- $\Theta$  weighting factor for AR part
- $\Phi$  weighting factor MA part
- *B* backshift operator
- $\nabla$  differential operator

with the backshift operator B connecting y(t-1) = By(t).

#### 2.2.2.5 Seasonal Models

Due to daily, weekly, yearly or other effects, many time series exhibit a periodic behaviour. The AR, AM, ARMA and ARIMA models can be utilized, but require to be extended by seasonal terms. According to Moghram and Rahman (Moghram et al. 1989) the extended ARIMA model (Equation 11) shows the ARIMA model of Section 2.2.2.4 extended by the seasonal terms  $\phi(B^S)$ ,  $\nabla^d \nabla^D_S$  and  $\theta(B^S)$ , capable of modelling one seasonality.

$$\Phi(B)\phi(B^S)\nabla^d\nabla^D{}_S y(t) = \Theta(B)\theta(B^S)a(t)$$
(11)

y(t)	electrical load
a(t)	white noise
Θ	weighting factor for AR part
$\theta(B^S)$	weighting factor AR part seasonal
$\Phi$	weighting factor MA part
$\phi(B^S)$	weighting factor MA part seasonal
B	backshift operator
$\nabla$	differential operator
$\nabla^D{}_S$	seasonal differential operator

Of course, the model introduced above can be further extended to account for two or more seasonalities, simply by adding the respective terms for further periodicity as introduced by Moghram and Rahman (*Moghram et al. 1989*)

$$\Phi(B)\phi(B^S)\phi'(B^{S'})\nabla^d\nabla^D{}_S\nabla^{D'}{}_{S'}y(t) = \Theta(B)\theta(B^S)\theta'(B^{S'})a(t)$$
(12)

u(t)	electrical load
a(t)	white noise
Θ	weighting factor for AR part
$\theta(B^S)$	weighting factor AR part seasonal
$\theta'(B^{S'})$	second weighting factor AR part seasonal
$\Phi$	weighting factor MA part
$\phi(B^S)$	weighting factor MA part seasonal
$\phi'(B^{S'})$	second weighting factor MA part seasonal
B	backshift operator
$\nabla$	differential operator
$ abla^D{}_S$	seasonal differential operator
$\nabla^{D'}{}_{S'}$	second seasonal differential operator

#### 2.2.2.6 Transfer Function Models

The models introduced in Section 2.2.2.1 to Section 2.2.2.5 express univariate timeseries y(t), based on their history and white noise. To account for the effect of other variables, a transfer function model is combined with a noise model n(t) discussed in Section 2.2.2.1 to Section 2.2.2.5, as shown in Figure 3 (Dale 1981).



Figure 3: Transfer Function Model according to Moghram and Rahman (Moghram et al. 1989)

#### 2.2.3 General Exponential Smoothing

Standard exponential smoothing (Holt-Winters Exponential Smoothing) was introduced by Winters (Winters 1960) and is able to capture one pattern of seasonality. An additive trend is assumed and the local slope  $T_t$  is estimated by smoothing subsequent differences  $(S_t - S_{t-1})$  on a local level  $S_t$ . The local seasonal index  $I_t$  is determined by smoothing the ratio of observed value  $X_t$  to local level  $S_t$  (Taylor 2003). According to Taylor (Taylor 2003), the k-step-ahead forecast  $\hat{X}_t(k)$  can be calculated by

$$\hat{X}_t(k) = (S_t + kT_t)I_{t-s+k}$$
(13)

with the level defined as

$$S_t = \alpha \frac{X_t}{I_{t-s}} + (1 - \alpha)(S_{t-1} + T_{t-1})$$
(14)

the trend defined as

$$T_t = \gamma (S_t - S_{t-1}) + (1 - \gamma) T_{t-1}$$
(15)

and seasonality defines as

$$I_t = \delta \frac{X_t}{S_t} + (1 - \delta)I_{t-s}$$
(16)

 $X_t$  observed value

 $\hat{X}_t(k)$  k-step-ahead forecast

- $\alpha, \gamma, \delta$  adjustable smoothing parameters
- $T_t$  local slope
- $S_t$  local level
- $I_t$  local s-period seasonal index

Standard exponential smoothing is limited to one seasonality. Taylor (*Taylor 2003*) extended the standard exponential smoothing to be better suited for short-term electricity demand forecasting by adding multi-seasonal capabilities.

### 2.3 Short-term forecasting using machine learning

Machine Learning algorithms can be categorized in two major architecture types: Generative Models and Discriminative Models. Generative models converge faster whereas discriminative models provide a better asymptotic error performance (*B. Liu et al. 2010*). Therefore, generative models are preferably used with little trainings data available and a discriminative approach is used with enough data at hand (*B. Liu et al. 2010*).

#### 2.3.1 Generative Models

Generative models learn the joint probability p(x, y) of inputs x and target y. Predicitons are made by calculating p(y|x) for all y for a given x and selecting the most likely as prediction for y (Ng et al. 2002).

Examples for generative models are Gaussian Process, Bayesian Networks, Hidden Markov Model, Restricted Boltzman Machine, Deep Believe Network and Generative Adverseral Network (*Han et al. 2019*).

#### 2.3.2 Discriminative Models

Discriminative models learn a direct mapping of input x to target y, minimizing the error function (decision risk) without estimating p(x, y), p(x|y) or p(y|x) ( B. Liu et al. 2010).

#### 2.3.2.1 Artificial Neural Network (ANN)

Neural networks are universally applicable and have been deployed to problems ranging from regression, classification to feature extraction, inference and others. The most common neural network configuration is the so-called Multilayer Perceptron (MLP) combined with Back Propagation (*Hecht-nielsen 1992, Wong 1991*).

An artificial neural network resembles the neural structure of the human cortex. A single neuron is shown in *Figure 4* with x being the input, w being the weight of the edge, b the neurons bias, y the output and F(x) the activation function. F(x) calculates the neuron output based on the sum of the neuron inputs. Based on *Figure 4*, the neuron can be described as *(S.-C. Wang 2003)* 

$$y = F(x * w + b) \tag{17}$$



Figure 4: Neuron model according to (S.-C. Wang 2003)

Multiple neurons grouped in layers form the ANN, with the first layer denoted as input layer and the last layer as output layer. *Figure 5* depicts a simple ANN. The output of the model is calculated by forward propagation and the model is refined during training using back propagation. (*Hirasawa et al. 1996, Che et al. 2011*).

ANNs have been used for forecasting tasks and have been combined with other techniques to improve prediction performance. Mellit and Pavan (*Mellit et al. 2010*) used an ANN to predict the solar irradiance of a PV plant in Italy. Heng et al. (*Heng et al. 1998*) introduced an ANN with genetic algorithm to perform short term load forecasting, which was subsequently extended by Liao et al. (*Liao et al. 2006*) to a fuzzy neural network with chaos genetic algorithms to perform short term load forecasting. Recently, Eseye et al. (*Eseye et al. 2019*) tested various feature selection



Figure 5: Artificial Neural Network with two Hidden Layers

algorithms and evaluated the forecasting performance of the selected feature subsets using a feedforward artificial neural network. "Dynamic neural network" introduced by Mordjaoui et al. (*Mordjaoui et al. 2017*) is a dynamic load forecasting approach based on artificial neural networks, able to adaptively learn patterns from the data.

Recurrent Neural Networks extend classical neural networks by connecting the neurons' output to their inputs, creating a closed loop and thus gaining the ability to memorize information involving trend and tendency. The training process is called Backpropagation-Through-Time (BPTT) (*Werbos 1990*) and has been described by Connor et al. (Connor et al. 1994), Anbazhagan and Kumarappan (Anbazhagan et al. 2012) and Guresen et al. (Guresen et al. 2011).

### 2.3.2.2 Convolutional Neural Network (CNN)

CNNs are inspired by a unique neuron structure in a cat's receptive fields, discovered in 1959 by two neurobiologists, Hubel and Wiesel (*Hubel et al. 1959*). LeCun and Bengio (*LeCun et al. 1995*) initially applied CNNs for speech, time series and image processing in 1995.

Similar to ANNs, a CNN consists of an input layer, multiple hidden layers and an output layer. Each layer contains activation functions such as Rectified Linear Unit (ReLu). Hidden layers come in three types: fully connected layers, convolutional layers and pooling layers. Convolutional layers learn to extract specific features of the sample (i.e. edges in an image) whereas pooling removes unnecessary information reducing the matrix size for subsequent processing and increasing processing speed. Fully connected layers have the neuron architecture of an MLP, connecting all of their input neurons and generating the output of the network (*Han et al. 2019*). Deep believe networks, a generative model, use a similar technique, but adding probability in the pooling process (*K. Lee et al. 1992*).

For univariate sequences, the CNN operates using a set of filters in the convolution layer and the output of the layer is obtained by computing the dot product between overlapping input and the filter weights in an autoregressive manner *(Han et al. 2019)*. Multivariate sequences can be thought of as 2D images, with time being one axis and variables the other *(Han et al. 2019)*.

In literature CNNs have been used to predict chaotic as well as real-world time series (Han et al. 2019). In the field of autonomous driving, Hoermann et al. (Hoermann et al. 2018) applied CNNs to predict data from multiple sensors in a down town scenario with multiple road users. Ding et al. (Ding et al. 2015) applied a dilated CNN architecture for event driven stock market prediction and Wang et al. (H.-z. Wang et al. 2017) deployed a combination of wavelet transform and CNNs for wind power forecasting. Further, CNNs have been heavily used for image recognition (Han et al. 2019).

#### 2.3.2.3 Long-Short Term Memory (LSTM)

RNNs, as introduced in Section 2.3.2.1 suffer from a vanishing or exploding gradient problem. The BPTT procedure depends exponentially on the weights for each timestep, failing to learn information over more than 5-10 timesteps (Han et al. 2019). The Long-Short Term Memory (LSTM) extends the RNN architecture by introducing a linear unit, the Constant Error Carousel (CEC) holding information that can be added to each timestamp. The error flow control of the CEC is performed using 'gates', the input gate controls the information added to the cell, the output gate controls the information contributed to the rest of the network and the forget gate controls the decay of the information. Therefore, LSTMs can maintain temporal information for many timesteps and it has been used in sequential data analysis, prediction and classification tasks (Hochreiter et al. 1997, Filonov et al. 2016) for both, univariate and multivariate (Fu et al. 2016, Filonov et al. 2016) problems.

### 2.4 Standardization and Normalization

Machine learning models learn a mapping from input variables to output variables. These variables might be given in different units (kWh, GWh, sec, hr, ...) and are likely to be differently scaled. Differences in scaling may increase the complexity of the problem being modelled and lead to large weight values of the model. Models with large weights are often unstable and prone to bad generalization abilities (*Brownlee 2020*). Standardization or normalization techniques can be applied to mitigate this problem.

#### 2.4.1 Normalization

Using normalization, the data is rescaled to a fixed range, usually to the range of 0 and 1, by subtracting the minimum value and dividing by the range of minimum and maximum value (*Witten et al. 2002*). Clearly, the minimum and maximum observable values have to be known or estimable (*Brownlee 2020*). A value is normalized as follows (*Brownlee 2020*)

$$y = \frac{x - x_{min}}{x_{max} - x_{min}} \tag{18}$$

with  $x_{min}$  being the minimum value and  $x_{max}$  the maximum value.

A value outside the minimum-maximum range is going to transform to a value below 0 or above 1.

#### 2.4.2 Standardization

Standardization is rescaling the observed data distribution to a mean of zero and a standard deviation of one. This is achieved by subtracting the mean from each value and dividing the result by the standard deviation *(Witten et al. 2002)*. A value is standardised as follows *(Brownlee 2020)* 

$$y = \frac{x - \mu}{\sigma} \tag{19}$$

Using standardization can prove more robust than normalizing, especially in respect to outliers. Furthermore, the values are not limited to a specific range. In this work, *RobustScaler* of scikit-learn is used to standardize data. *RobustScaler* uses percentiles to determine mean and standard deviation, making it even more resilient against outliers (*s. scikit 2020*).

## 3 Methodology

### 3.1 Data Analysis Pipeline

A standardized process is utilized to perform the machine learning experiments and *Figure 6* depicts the overall data analysis pipeline. First, the data is loaded and all necessary representation specific preprocessing (merging of files, adjustment of the representation of numbers, ...) is performed. Second, the data is manually inspected (*Section 3.1.1*). If a data specific preprocessing is necessary, it is conducted as third step of the data analysis pipeline (*Section 3.1.2*). The implementation of the first three steps is highly specific for each dataset, aiming to transform each into a coherent data structure usable by all following processing steps. After pre-processing, a baseline, serving as a performance reference for more elaborate algorithms, is established (*Section 3.2*). All processes relevant for training deep learning models are discussed in *Section 3.3*, relying on the baseline to discriminate well and poorly performing algorithms. Finally, the results are compared across all datasets available in *Section 5*.



Figure 6: Applied Data Analysis Pipeline

### 3.1.1 Manual Data Exploration

The goal of the manual data exploration is to get a feeling for the processed data and to answer the following key questions:

- (a) Do outliers exist?
- (b) Is there a significant trend?
- (c) Are recurring patterns observable?

For the use-case of electric demand prediction, load peaks (outliers) can worsen the prediction outcomes and must be removed. Outlier removal is introduced in *Section 3.1.2.* 

A trend is a continuous change, for example an increase or a decrease, of electricity demand over time, beyond seasonal patterns. Since neither of the datasets introduced in *Section 4.2* experiences trend, it will not be elaborated further.

The presence of recurring patterns impacts feature selection for the algorithms used. All available datasets are experiencing recurring daily, weekly and annual patterns, as shown in *Section 4.2*. Therefore, the univariate power consumption is extended by calendric features (*Section 3.3.1*), to broaden the algorithms' prediction basis and improve prediction performance.

#### 3.1.2 Pre-Processing Data

The only dataset requiring further pre-processing is Dataset 1 by Company A introduced in *Table 1*, showing major load peaks in manual data exploration (*Section 4.2.1*).

Without considering these load peaks as outliers and removing them, the regular electric load pattern would be reduced in importance during normalization and significantly harm prediction performance.

*Listing 1* shows the code used to remove the outliers. The z-score threshold of *Line 4* is selected empirically based on a all-time load plot, to remove all outliers excelling the regular electric load pattern.

Listing 1: Outlier removal for Dataset 1 according to (stackoverflow 2020(c))

```
1 import pandas as pd
2 from scipy import stats
3 df = pd.read_pickle("dataset_1.pkl")
4 mask = (np.abs(stats.zscore(df['power'])) > 0.18)
5 df.power = df.power.mask(mask).interpolate()
```

### 3.2 Baseline

A baseline is a meaningful reference point, a basis for the comparison of results of deep learning algorithms. Usually, a baseline is the simplest possible prediction, a random result or the most common prediction approach (*Brownlee 2014*). This work utilizes the prediction method used by Company B and Company C, the so called "last-year-consumption" approach, to construct a baseline. In the "last-year-consumption", the electric energy consumption of the previous year is shifted to match the corresponding week days (Monday to Monday, Tuesday to Tuesday, ...) of the current year and is compensated for holidays according to *Listing 2*. The for loop of *Line 18* creates the averages to compensate past holidays, becoming work days, in the prediction period, with the average consumption of a workday ("avg\_workday") and to compensate past work days turning into holidays with the average consumption of a holiday ("avg\_holiday"). In the for-loop of *Line 30*, those averages are applied to the prediction in cases of holiday/workday mismatches.

Listing 2: Code generating the Baseline

```
data #Standardized electric load consumption data as pandas dataframe
1
   # 2018 is used as prediction for 2019
2
3
   split date = datetime.datetime(2019,1,1,0,0,0)
   days = datetime.timedelta(364)
4
   start_date=split_date-days #Algorithm takes values starting from beginning of
5
       2018
   stop date = split date + datetime.timedelta(365) #Algorithm takes values until
6
        end of 2019
   historic data = data.loc[start date:stop date]
7
8
   historic index = historic data.index
   future_index = data.loc[split_date:stop_date].index
9
10
   future year = np.zeros(data.loc[split date:stop date].shape[0])
11
12
   past year shape = historic data.shape[0] - future year.shape[0]
13
   count offdays = 0
   sum offdays = 0
14
15
   count workday = 0
16
   sum workday = 0
17
```

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```
for i in range(0, past year shape):
18
19
            ci = historic_index[i] #ci = current index
20
            if (ci in at_holidays) or (calendar.weekday(ci.year, ci.month, ci.day)
                >=5)
21
                     count offdays = count offdays + 1
22
                     sum offdays = sum offdays + historic data.iloc[i:i+1].values
                         [0][0]
23
            else:
24
                     count workday = count workday + 1
25
                     sum workday = sum workday + historic data.iloc[i:i+1].values
                         [0][0]
26
27
   avg workday = sum workday/count workday
28
    avg offday = sum offdays/count offdays
29
30
    for i in range(0, future_year.shape[0]):
            if(historic_index[i] in at_holidays)and(future_index[i] in at_holidays):
31
32
                     future_year[i] = historic_data.iloc[i:i+1].values[0][0];
33
            else:
34
                     if (future index[i] in at holidays):
35
                             future_year[i] = avg_offday;
36
                     else :
37
                             if (historic index [i] in at holidays):
38
                                      future_year[i] = avg_workday
39
                             else :
40
                                      future year[i] = historic data.iloc[i:i+1].
                                          values [0][0];
```

## 3.3 Deep Learning Pipeline

Similar to the data analysis pipeline introduced in *Figure 6*, the deep learning experiments are implemented as a modular process, depicted in *Figure 7*.

The process starts by loading the pre-processed data and transforming the univariate electric load data into a multivariate dataset by adding calendric information as additional features (*Section 3.3.1*). Adding calendric information simplifies learning date and time based recurring patterns. Next, the available data is split into training and test sets (*Section 3.3.2*) and the actual training loop is started (*Section 3.3.3*). Finally, the methods to compare the results for each algorithm and dataset are introduced in *Section 3.4* 



Figure 7: Deployed Deep Learning Pipeline

#### 3.3.1 Calendric Information Extraction

The datasets described in *Section 4.2* are limited to univariate historic electric consumption data, making it difficult to identify recurring patterns. Electric load demand is considered to be highly correlated with calendaric events, as for example time of day, weekday, overall season or holidays.

Providing algorithms with primed calendaric information enables them to directly learn the correlation between time patterns and energy consumption. *Listing 3* depicts the function used to add calendric information to the dataset.

Listing 3: (	Calendric	Feature	Extraction
--------------	-----------	---------	------------

```
import holidays
def extract calendric information(data):
        at holidays = holidays.Austria()
        data ['dow']=data.index.dayofweek
        data ['m year']=data.index.month
        data ['q_hour'] = np.round(data.index.minute/15)
data ['hour']=data.index.hour
        data ['isWorkday']=1 #Initialising 'isWorkday' with 1
        data['beforeHoliday']=0 #Initialising 'beforeHoliday' with 0
         filter1 = data.index.dayofweek==5 #Saturday
         filter2 = data.index.dayofweek==6 #Sunday
        #Setting 'isWorkday' to zero for Saturdays data.loc[filter1, 'isWorkday'] = 0
                   'isWorkday' to zero for Sundays
        #Setting
                            'isWorkday'] = 0
        data.loc[filter2,
        #The following loop iterates over all datapoints and assesses if
        #the datapoint is indeed a workday and the next day will be a workday.
         for index, row in data.iterrows():
                 x, row in data...terren.()
if(index in at_holidays):
_______data_loc[index, 'isWorkday']=0
                 index offset = index+pd. DateOffset(1)
                 return data
```

### 3.3.2 Training/Test Split

Machine learning algorithms infer rules, based on the data they are trained on, becoming proficient on the training data. As the algorithms are deployed on new, unseen data, it is important to assess their generalization abilities. This is achieved by applying the algorithms to the test set, comprised by data not used for training. It is created by splitting the provided dataset into a larger training set and a smaller test set. The test set must never be used for training or training decisions. Therefore, the training set is split further to create the actual training set and a validation set. The validation set is used during the model training process to determine the models performance after every epoch.

The algorithms in this work are designed to learn annual patterns, thus the minimum duration of the training data must be at least one year, to model one full annual cycle and the minimum duration of the test data should be one year too, to measure the performance on one full annual cycle. Dataset 2 is the smallest, providing a total of 21 month from January 2018 to September 2019 (*Section 4.2.2*). As the other datasets cover significantly larger timespans and include the year 2019 too, Tuesday

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01.01.2019 00:00 is selected as universal training/test split date, defining all measurements of 2019 as test data. *Listing 4* shows the code used to split training and test set. During training, the training set will be randomly split into actual training and validation data for each subsequent training epoch, preventing the model from being subject to bias.

Listing 4: Performing Training/Test Split according to (stackoverflow 2020(b))

```
import pandas as pd
1
2
   import datetime
3
   ## This function requires a splitting date, not a splitting index ##
4
5
    def training test split (data, splitting date):
            training = data.loc[data.index<splitting_date]
6
7
            test = data.loc[data.index >= splitting_date]
8
            return training, test
9
10
   split date = pd. datetime (2019, 1, 1, 0, 0, 0)
11
   training , test = training test split(data.copy(),split date)
```

### 3.3.3 Model Training Process

#### 3.3.3.1 Normalization

The deep learning algorithms used for this thesis operate best, if the provided data is mapped to the range of 0 to 1. This is achieved by normalizing the training set as introduced in *Section 2.4.1*, using MinMaxScaler of the sklearn library. *Listing 5* depicts the respective code.

```
Listing 5: Instatiation of normalization object according to (scikit 2020)
1 scalingTransformer = MinMaxScaler(feature_range=(0,1)).fit(training.copy())
```

scalingTransformer is calibrated using only the training set, assuming the test set would not be available in production setting at the time of training. It is applied to the datasets in the *create\_supervised\_trainingset* function (*Line 10*), introduced in *Listing 6* 

### 3.3.3.2 Sample Generation

The deep learning algorithms require a supervised dataset with each input X mapped to the corresponding output Y and each of these input-output pairs is called a sample. The extended electric load demand is provided in a stream of datapoints as shown in *Figure 8*, one measurement for each feature every 15 minutes and has to be transformed to constitute a supervised problem. *Listing 6* shows the function *create supervised trainingset*, used to dynamically transform the raw data.

Listing 6: Transforming Time Series Data to Supervised Learning Problem inspired by (*Brownlee 2017*)

```
1 def create_supervised_trainingset(data, output_shape, n_steps_in, n_steps_out,
    time_shift=1, univariate=True, scalingTransformer=None):
2    n_steps_in = int(n_steps_in)
3    n_steps_out = int(n_steps_out)
4    time_shift = int(time_shift)
5    #Normalization has to be done, before creating the supervised dataset
6    #scalingTransformer has been initialized in Listing 5
7
```

```
if (scalingTransformer!=None):
        orig = data.copy()
        data = pd.DataFrame(scalingTransformer.transform(data))
if(time shift<1):</pre>
        return None
else :
       X, y = list(), list()
        i = 0
        end_y = end_x + n_steps_out
               seq_x = data.iloc[i:end_x,:].to_numpy()
                seq_y = data.iloc[end_x:end_y,0].to_numpy()
               X.append(seq x)
               y.append(seq_y)
                i = i+time shift
       Xa = np.array(X)
        ya = np.array(y)
        if (univariate)
               Xa=Xa[:,:,0]
                if(output_shape == "3D"):
                       Xa = np.expand dims(Xa, -1)
       ## Multivariate datasets generate a three-dimensional
            datastructure. For ANN/MLP algorithms a two-dimensional
            structure is required.
        if (output shape="2D" and Xa.ndim>2):
               ## Flattening, with keeping the amount of samples the
                   same ##
               Xa = Xa.reshape(Xa.shape[0], Xa.shape[1]*Xa.shape[2])
#2D: [sample, timesteps]
#3D: [samples, timesteps, features]
return Xa, ya, data, orig
```



Figure 8: Structure of original data

In Line 17 to Line 26, the data is transformed to a three-dimensional structure. Assuming multivariate data with N features, the original dataset is grouped into samples with a fixed number ( $\#steps\_in$ ) of measurements per feature to form the input X and  $\#steps\_out$  subsequent measurements of the target feature feature1 are grouped to form the output Y. This work aims to predict a full day, day-ahead and therefore  $\#steps\_out$  is set to 96, the number of quarter hours a day.  $\#steps\_in$  is a variable for hyperparameter optimization, introduced in Section 3.3.3.4. Line 24 utilizes the variable time\\_shift, determining the step-size between subsequent samples. time\\_shift = 1 produces the maximum overlap, shifting only 15 minutes

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for each sample whereas time\_shift = 96 shifts the subsequent samples by a full day, not producing an overlap. This is directly impacting the number of samples drawn from a given dataset, expanding the supervised dataset for small original datasets for better learning outcomes (useful for Dataset 2) and shrinking down large datasets to increase training speed (useful for Dataset 1).

The resulting three-dimensional structure is shown in *Figure 9* and required for CNN and LSTM models.



Figure 9: 3D shaped supervised dataset

Artificial neural networks require a two dimensional datastructure, each sample represented by one line in the matrix. The three-dimensional datastructure is folded *(Kourti 2003)* into a two dimensional datastructure, by keeping the sample-axis static and flattening the two-dimensional time-feature matrix (*Line 34*). The result is an array with the data of each feature subsequently aligned, shown in *Figure 10* 



Figure 10: 2D shaped supervised dataset with m as #steps in and p as #steps out

#### 3.3.3.3 Model Definition

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41 42 The function *define\_model* (*Listing 7*) is designed to easily support further models and to be included in automated hyperparameter optimization (*Section 3.3.3.4*). Currently, basic artificial neural networks (MLP in *Listing 7*), CNNs and LSTMs are supported. The number of neurons, number of hidden layers as well as kernel and pooling size for CNNs are variables for hyperparmeter optimization.

```
Listing 7: Deep Learning Model Definition according to (Brownlee 2018c)
def define model(model,config, actv='relu'):
        input_shp , n_output , n_neurons , batch_size , hidden_layers , n_kernel ,
            n pool, shapeX, shapeY = config
        n neurons = int(n_neurons)
        batch size=int(batch size)
        hidden layers = int (hidden layers)
        n_kernel = int(n_kernel)
        n pool =int(n pool)
        if (model == "MLP"):
                 model = tf.keras.models.Sequential()
                 model.add(tf.keras.layers.Dense(n neurons, activation=actv,
                     input_shape=input_shp))
                    i in range(1, hidfden_layers):
                         model.add(tf.keras.layers.Dense(n neurons, activation=
                             actv))
                 model.add(tf.keras.layers.Dense(n output[0]))
                 model.compile(loss='mse', optimizer='adam')
        if (model == "CNN"):
                 model = tf.keras.models.Sequential()
                 model.add(tf.keras.layers.Conv1D(filters=n neurons, kernel size=
                     n_kernel, activation=actv, input_shape=input_shp))
                 for
                    i
                      in range(1, hidden layers):
                         model.add(tf.keras.layers.Conv1D(filters=n neurons,
                 kernel_size=n_kernel, activation=actv))
model.add(tf.keras.layers.MaxPooling1D(pool_size=n_pool))
                 model.add(tf.keras.layers.Flatten())
                 model.add(tf.keras.layers.Dense(n_output[0]))
                 model.compile(loss='mse', optimizer='adam')
        if (model == "LSTM"):
                 model = tf.keras.models.Sequential()
                 if(stateful)
                         batch_input_sh = (batch_size,)+input_shp
                         model.add(tf.keras.layers.Lambda(lambda x:x,
                             batch input shape=batch input sh))
                 else:
                         model.add(tf.keras.layers.Lambda(lambda x:x, input shape
                             =input_shp))
                 for i in range(1, hidden layers):
                         model.add(tf.keras.layers.LSTM(n neurons,
                             return_sequences=True, stateful=stateful))
                 model.add(tf.keras.layers.LSTM(n_neurons, stateful=stateful))
                 model.add(tf.keras.layers.Dense(n_output[0]))
                 model.compile(loss='mse', optimizer='adam')
        return model
```

### 3.3.3.4 Hyperparameter Optimization

Hyperparameter optimization is the problem of optimizing a loss function, by searching the space of possible model and training process configurations (J. S. Bergstra

*et al. 2011, J. Bergstra et al. 2015)* to improve the overall model performance. Hyperparameters can be discret, ordinal or continuous values (*J. S. Bergstra et al. 2011*). Possible approaches for hyperparameter optimization are (*J. Bergstra et al. 2015*)

- (a) Manual tuning
- (b) Grid search
- (c) Random search
- (d) Bayesian search

Manual hyperparameter optimization relies on human experience and quickly becomes infeasible for high-dimensional search spaces. Grid-search sets fixed and discrete values to test each algorithm, fixing the parameters to a specific grid. In random search, parameters are selected randomly, within some pre-defined bounds. For high-dimensional hyperparemeter optimization problems, random search has proven advantageous over manual- or grid-search (*J. Bergstra et al. 2015*). The Bayesian search strategy executes a few random search runs to obtain measurements of the multidimensional fitness surface of the loss function, before applying the Bayesian search gradient in gradient decent manner to approximate the model configuration with minimized loss function (*J. Bergstra et al. 2015*).

This work uses *hyperopt*, a Bayesian search library for python introduced by (*J. Bergstra et al. 2015*).

The tuned hyperparameters are *learning rate*, *number of neurons*, *activation function*, *number of hidden layers*, *input data window size in days ("days\_in")*, *batch size* as well as *kernel size* and *pooling window size* for CNNs. The search space is defined according to *Listing 8*. The desired model algorithm was selected manually for each experiment.

Listing 8: Hyperopt Search-Space Definition according to (J. Bergstra et al. 2013)

The *hyperopt* function "*fmin*" expects the space object defined in *Listing 8* and the loss function to be optimized. In this case, the loss function (objective function) defines the individual models to be trained and evaluated, as shown in *Listing 9*. "*EPOCHS*" is a global variable, defining the number of training epochs for one model. "*params*" is the configuration object for one specific experiment created by hyperopts' "*fmin*" based on the space object defined in *Listing 8*.

6 7 8

9

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```
def objectiveFunction(params):
1
2
            epochs=EPOCHS
3
            batch_size=100
4
            kernel
                   size=0
            n_pool=0
6
            actv = params['actv']
            hidden layers = params ['hidden layers']
            learning_rate=params['learning_rate']
8
9
            neurons=params['neurons']
10
            univariat = params['univariat_data']
            days_in = params['days_in']
            batch_size = int(params['batch_size'])
14
            algo object = params['model algorithm']
15
            model algorithm = algo object ['model algorithm']
            output shape = algo object ['data output shape']
            if (model algorithm == 'CNN'):
                     kernel_size = algo_object['kernel_size']
n_pool=algo_object['n_pool']
20
22
            n_steps_in=int(96*days_in), n_steps_out=96, univariate=univariat,
                time_shift=global_timeshift)
            model = define_model(model_algorithm,[Xtr.shape[1:],ytr.shape[1:]
                neurons, epochs, batch size, hidden layers, kernel size, n pool, Xtr.
                shape, ytr.shape], actv=actv)
            doShuffle=True
            if(take_best_val model):
                     callbacks.append(TakeMinWeights())
28
            history = model.\,fit\,(Xtr\,,ytr\,,epochs=epochs\,,batch\_size=batch\_size\,,
                validation_split=0.2, shuffle=doShuffle, callbacks=callbacks,
                verbose=verbose))
29
30
31
            val losses = history.history['val loss']
32
            training losses = history.history['loss']
            if(take_best_val_model):
34
                     val loss=min(val losses)
35
            else:
                     val_loss = val_losses [len(val_losses)-1]
            of connection = open(out file, 'a')
38
            writer = csv.writer(of_connection)
            time_diff = int(time.time())-gobaltime
            #All results of a hyperopt run are collected in a csv for rapid
                evaluation
            writer.writerow([time diff, val loss, params, val losses, training losses
                 time.time()])
42
            #Independent of the model performance, each model is saved for later
                evaluation using the test dataset.
            model path = trainpath+'/models/hyperopt_search_%s_model_%s'%(
                experiment nr, time diff)
            of connection.close()
45
            model.save(model_path)
46
            return {'loss': val_loss, 'params': params, 'history': history.history,
status':STATUS_OK, 'model':model, 'train_loss':training_losses}
```

#### **Performance Evaluation** 3.4

#### 3.4.1 **Performance Metrics**

Performance metrics are vital components for the evaluation of regression models (Botchkarev 2019). This work utilizes four performance metrics, the mean square er-

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ror, the root mean square error, the mean absolute error, and the cumulative absolute error to evaluate the forecasting accuracy. These metrics allow comparison between models and with the baseline.

Mean square error (MSE) is the mean value of the sum of squared differences, calculated as follows

$$MSE = \frac{1}{N} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$
(20)

The mean absolute error (MAE) is the mean value of the sum of absolute differences (*Bouktif et al. 2018*), calculated as follows

$$MAE = \frac{1}{N} \sum_{i=1}^{N} |y_i - \hat{y}_i|$$
(21)

The root mean square error (RMSE) is the root of the mean value of the sum of squared differences (MSE), calculated as follows (*Bouktif et al. 2018*)

$$RMSE = \sqrt{\frac{1}{N} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2}$$
(22)

The RMSE is large for large errors and penalizes outliers more severely than MAE when used during model training *(Bouktif et al. 2018)*. The cumulative absolute error (CAE) is the sum of absolute differences and is used to assess the absolute improvements. The CAE is calculated according to *Equation 23*.

$$CAE = \sum_{i=1}^{N} |y_i - \hat{y}_i|$$
 (23)

For all equations listed above,  $y_i$  is the observed value,  $\hat{y}_i$  the predicted value and N the total number of observations.

#### 3.4.2 Training and Validation Loss Plots

Training and validation loss plots give a good indication, whether a training process is going to deliver promising results, or not. The training loss value for a specific epoch is the mean loss of each batch processed within. The validation loss value of a specific epoch is the error of the model applied to the validation set. Plotting training- and validation loss for each epoch of a models training can give valuable insights of training performance. *Figure 11* shows an ideal epoch-loss plot with the training loss converging towards zero and the validation loss following closely. In *Figure 12*, the validation loss starts diverging from the training loss at epoch 60. This indicates that the model is overfitting, a common problem of deep learning algorithms. When overfitting occurs, the algorithm learns the trainings data too closely, sacrificing generalization abilities. According to Brownlee (*Brownlee 2018b*) possible countermeasures are

#### (a) Weight Regularization

An indicator for overfitting can be large network weights. With large network weights, a small change in network input might result in a large change in the network output, reducing the networks reliability. Weight regularization encourages small weights during network training. (*Brownlee 2018g*)

#### (b) Activity Regularization

Activity regularization encourages neural networks to learn sparse features or internal representations of raw observations. (*Brownlee 2018e*)

#### (c) Dropout

Dropout is a computationally cheap way to regularize a deep neural network. It works by probabilistically removing inputs to a layer, which has the effect of simulating many networks with a different network structure each. (Brownlee 2018f)

### (d) Noise

Noise has shown to have a regularizing effect on under-constrained neural network models with a small training dataset. (*Brownlee 2018d*)

### (e) Early Stopping

Choosing the training duration is a major challenge in training neural network models. Too little training will result in underfitted training- and test sets. Too much training will result in an overfitted model on the training set and poor performance on the test set. Early stopping aborts the training process and saves the model on a given condition before the model starts overfitting the training data, improving generalization. (*Brownlee 2018a*)



Figure 11: Ideal training and validation loss progression



Figure 12: Training and validation loss progression with overfitting

In this thesis, a combination of dropout, weight constraint and a special form of early stopping ("take\_best" approach) have been applied.

By utilizing *hyper\_opt* hyperparameter optimization, a multitude of models is trained in one batch, with the same number of epochs each. To select the best model before overfitting starts, the *'take\_best'* methodology is applied as callback to the model training process (*Listing 9, Line 27*). In this methodology, the best performing weights on the validation set (*val\_loss*) are stored (*Listing 10, Line 19*) and reloaded into the model after training has finished (*Listing 10, Line 23*). This ensures that the best model of a training is returned and stored as final model.

```
Listing 10: Callback Function "TakeMinWeights" inspored by (Core 2020)
#Callback class, provided to TensorFlow
class TakeMinWeights(tf.keras.callbacks.Callback):
        def __init__(self):
                super(TakeMinWeights, self). init ()
        #Initialize best weights with none.
        self.best weights = None
        def on train begin(self, logs=None):
                # Initialize the best as infinity.
                self.best = np.lnf
        def on_epoch_end(self, epoch, logs=None):
                current = logs.get('val_loss')
                #Check if current validation loss is better, than the best
                 if np.less(current, self.best):
                        #If yes, replace.
self.best = current
                         self.best_weights = self.model.get_weights()
        def on train end(self, logs=None):
                #Load best weights into model, before saving.
                self.model.set weights(self.best weights)
```

#### 3.4.3 Result Evaluation

The obtained prediction is transformed back to the original space. In production settings, the prediction in original space would be used for demand planning.

To compare the results across datasets, standardisation (*Section 2.4.2*) is applied to the predicted data. *Listing 11* shows the function *scale\_backY* used to transform the prediction from normalized to original space (*Line 1*) and the function *evalStan-dardScaling* used to standardize the predicted data (*Line 7*).

Listing 11: Transformation of Predicted Data inspired by (*stackoverflow 2020(a*))

```
def scale_backY(yData, scalingTransformer, nrColumns):
    y_reshaped = np.zeros((yData.shape[0]*yData.shape[1],nrColumns))
    y_reshaped[:,0] = np.reshape(yData,(yData.shape[0]*yData.shape[1]))
    scaled_back = scalingTransformer.inverse_transform(y_reshaped)
    return scaled_back[:,0]
def evalStandardScaling(prediction, ground_truth):
    #Standard Scaler
    df=pd.DataFrame(ground_truth)
    df= df.append(pd.DataFrame(prediction))
    df.reset_index()
    robust_transformer = RobustScaler().fit(df)
    pred_rb = robust_transformer.transform(pd.DataFrame(prediction))
    gt_rb = robust_transformer.transform(pd.DataFrame(ground_truth))
    return pred_rb, gt_rb
```

Standardized predicted data is used for all plots and performance metrics of *Section 4*.

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# 4 Experiments and Results

## 4.1 Infrastructure and Software

The data preprocessing and baseline experiments were run on a Lenovo ThinkPad Yoga 370 with an Intel Core i7 2.9 GHz CPU and 16GB RAM running Windows 10. Data preprocessing and baseline experiments were conducted with Python 3.7.3, and Spyder 3.3.3 was used as IDE. Additionally the python packages pandas, matplotlib, datetime, sklearn, calendar, holiday, hyperopt and numpy have been used.

Machine learning experiments were executed on Google Cloud Compute Engine using the provided Deep Learning VM Image in region europe-west1-d with Tensor-Flow 2.1 environment on a machine with 2 CPUs, 13 GB RAM and a NVIDIA Tesla K80 x1 GPU. Code was deployed using pre-configured Juypter Lab.

## 4.2 Introduction and Exploration of Datasets

In this thesis three real-world industrial electricity consumption datasets have been analysed, introduced in *Table 1*.

Table 1: Introduction of Datasets					
Company A	Dataset 1	The provided dataset has been recorded at a plant			
		producing medical packaging.			
Company B	Dataset 2	The facility in which this data set was recorded			
		produces packaging for food & beverages, fast-			
		moving-consumer-goods and hygiene products.			
Company C	Dataset 3	This dataset was provided by an electric utility com-			
		pany aiming to improve their in-house forecasting.			
		It was recorded at an industrial plant, however the			
		goods produced are unknown.			

## 4.2.1 Dataset Exploration Company A

Company A is a plastic packaging manufacturer and the given plant is producing pharmaceutical packaging. The dataset holds five years of electric power consumption data, between January 2013 and December 2019. *Figure 13* depicts the electric power consumption for 2018, showing major load peaks in October and December. It is known that this company is experiencing load peaks frequently. For this work, the load peaks will be considered as outliers and are removed according to *Section 3.1.2. Figure 14* shows the electric power consumption of Company A for 2018 with outliers removed. Some peaks still remained, but within reasonable bounds. *Figure 14* indicates a cyclic yearly pattern with a increased energy consumption in Summer, which is supported by *Figure 15*, showing monthly box plots for 2018 and 2019. The box plot of *Figure 15* suggests a seasonal pattern.

*Figure 16* shows the power consumption in the range February 1<sup>st</sup> 2018 until February 14<sup>th</sup> 2018, with February 3<sup>rd</sup> and February 10<sup>th</sup> being Saturdays and February



Figure 13: Electric power consumption of Company A in 2018



Figure 14: Electric power consumption of Company A in 2018 with outliers removed

4<sup>th</sup> and February 11<sup>th</sup> being Sundays. A drop in power consumptions can clearly be seen for weekends, however, *Figure 16* does not indicate any further weekly patterns.

*Figure 17* shows the power consumption of two subsequent days, Tuesday February 6<sup>th</sup> 2018 00:00 until Wednesday February 8<sup>th</sup> 2018 23:59, not indicating a predominant inter-day pattern, suggesting a 4-shift-work cycle being run by Company A.



Figure 15: Electric power consumption box plot of Company A in 2017, 2018 and 2019



Figure 16: Electric power consumption of Company A in the range February  $1^{\rm st}$  2018 until February  $14^{\rm th}$  2018



Figure 17: Electric power consumption of Company A in the range February  $6^{th}$  2018 00:00 until February  $8^{th}$  2018 23:59

#### 4.2.2 Dataset Exploration Company B

Company B is a paper goods manufacturer and this specific plant is producing packaging for food & drinks, fast-moving-consumer-goods and hygiene products. The dataset provides one year and nine month of electric power consumption data, between January 2018 and September 2019. *Figure 18* depicts the electric power consumption for 2018, not showing any significant outliers nor indicating any seasonal trend. This is supported by *Figure 19* showing the box plot for 2018 and 2019. The median drop in *2018-12* of *Figure 19* is due to a two week production stop during the Christmas period.



Figure 18: Electric power consumption of Company B in 2018

*Figure 20* shows the power consumption in the range February 1<sup>st</sup> 2018 until February 14<sup>th</sup> 2018, with February 3<sup>rd</sup> and February 10<sup>th</sup> being Saturdays and February 4<sup>th</sup> and February 11<sup>th</sup> being Sundays. A drop in power consumptions can clearly be seen for weekends. The end of each workday is clearly identifiable by an overnight drop in power consumption.

*Figure 21* shows the power consumption of two subsequent days, Tuesday February 6<sup>th</sup> 2018 00:00 until Wednesday February 8<sup>th</sup> 2018 23:59 with the power consumption starting at 5:00 and dropping again at 21:00, representing a total 16 hours of active work, thus suggesting a non-overlapping two shift work cycle.



Figure 19: Electric power consumption box plot of Company B in 2018 and 2019



Figure 20: Electric power consumption of Company B in the range February  $1^{\rm st}$  2018 until February  $14^{\rm th}$  2018



Figure 21: Electric power consumption of Company B in the range February  $6^{th}$  2018 00:00 until February  $8^{th}$  2018 23:59

#### 4.2.3 Dataset Exploration Company C

The dataset of Company C has been provided by a utility company and its field of operation is unknown. The dataset holds five years of electric power consumption data, between November 2015 and February 2020. *Figure 22* depicts the electric power consumption for 2018, indicating two weeks of work interruptions in August 2018 and three weeks in October 2018, not showing any significant load peaks. The box plot shown in *Figure 23* suggests a minor seasonality, with electricity consumption having its yearly minimum between July and August.



Figure 22: Electric power consumption of Company C in 2018

*Figure 24* shows the power consumption in the range February 1<sup>st</sup> 2018 until February 14<sup>th</sup> 2018, with February 3<sup>rd</sup> and February 10<sup>th</sup> being Saturdays and February 4<sup>th</sup> and February 11<sup>th</sup> being Sundays. A drop in power consumptions can clearly be seen for weekends. The end of each workday is clearly identifiable by an overnight drop in power consumption. It is important to point out, that some Fridays also show a significant drop in power consumption compared to the other workdays, suggesting a reduced workload.

*Figure 25* shows the power consumption of two subsequent days, Tuesday February 6<sup>th</sup> 2018 00:00 until Wednesday February 8<sup>th</sup> 2018 23:59 with the power consumption starting at 6:30 and dropping again at 16:30, representing a total 10 hours of active work, thus suggesting a overlapping two shift work cycle.



Figure 23: Electric power consumption box plot of Company B in 2017, 2018 and 2019



Figure 24: Electric power consumption of Company C in the range February  $1^{\rm st}$  2018 until February  $14^{\rm th}$  2018



Figure 25: Electric power consumption of Company C in the range February  $6^{th}$  2018 00:00 until February  $8^{th}$  2018 23:59

## 4.3 Demand Prediction

In this Section, the prediction results for the baseline algorithm, neural network models, convolution neural network models and long-short term memory models are discussed for each dataset independently. The overall results across datasets are discussed in Section 5

To assess the prediction results across models, the performance metrics introduced in *Section 3.4* are used and the predicted and actual ("ground truth") standardized electricity consumption is plotted for the test set.

Additionally, four comparison time ranges have been selected, aiming to obtain a zoomed-in view on time periods of interest:

- (a) **Zoom 1** (1.3.2019 16.3.2019) was selected to represent two normal weeks, without holidays
- (b) Zoom 2 (13.5.2019 26.5.2019) was selected because Monday, March 21<sup>st</sup> 2019 was Whit Monday, a public holiday, and is therefore directly impacting the baseline predictions
- (c) Zoom 3 (17.6.2019 1.7.2019) includes Corpus Christi 2019 (Thursday June 20<sup>th</sup> 2019), a public holiday
- (d) Zoom 4 (29.7.2019 25.8.2019) includes Assumption Day 2019 (August 15<sup>th</sup> 2019) and company holidays or maintenance shutdowns for Company C

The performance metrics presented in the following sections have been calculated using standardized data (Section 2.4.2) and are without unit.

## 4.3.1 Processing Dataset 1

Following, Dataset 1 is predicted using the Baseline and the best performing neural network model, convolution neural network model and long short-term memory model.

#### 4.3.1.1 Baseline

*Figure 26* shows the baseline prediction, as introduced in *Section 3.2*, for Dataset 1. The overall, seasonal pattern of 2018 is matching the seasonal pattern of 2019, but the predictions show significant divergence with an overall RMSE of 0.798 and absolute error of 20115, suggesting improvement potential. The error statistics listed in *Table 2* have been calculated using standardized energy demand and therefore do not have a unit. The drop in electricity consumption at the end of 2019 is explained by Christmas and New-Year holidays. *Table 2* lists the performance metrics for the baseline of Dataset 1.

*Figure 27* depicts Zoom 1 of the baseline prediction for Dataset 1, suggesting major divergences between ground truth and prediction. This is confirmed by a high RMSE value, compared to the other zoom segments.

*Figure 28* is depicting Zoom 2, with the algorithms holiday compensation of Whit Monday 2020 clearly recognisable from May 20<sup>th</sup> to May 21<sup>st</sup>. For Zoom 2, the

I di	DIE Z. Datas	el I Dasein		
	MAE [Wh/Wh]	MSE [Wh/Wh]	RMSE [Wh/Wh]	CAE [Wh/Wh]
Full	0.574	0.637	0.798	20115
Zoom 1	0.524	0.411	0.641	754
Zoom 2	0.327	0.169	0.411	408
Zoom 3	0.544	0.438	0.662	731
Zoom 4	0.339	0.177	0.420	879

Table 9. Detect 1 Deceline Emery Cresienter

historic values used for the baseline prediction, show a better resemblance with the ground truth than in Zoom 1, confirmed by a lower RMSE value of 0.169.

Figure 29 shows the baseline prediction for Zoom 3. The holiday correction to the mean off-days is clearly identifiable. For Zoom 3, predicted consumption is higher than actual consumption levels resulting in a higher RMSE value compared to Zoom 2 and a similar error compared to Zoom 1.

Figure 30 is showing the baseline prediction for Zoom 4. The prediction approximates the ground truth comparatively well, resulting in a low RMSE value of 0.177. The holiday compensations introduced by the baseline for 15.8.2018 (Assumption Day 2018) and 16.8.2019 (Assumption Day 2019) are clearly visible.



Figure 26: Baseline Prediction for Dataset 1



Figure 27: Baseline Prediction for Dataset 1, Zoom 1 (01.03.2019 until 16.03.2019)



Figure 28: Baseline Prediction for Dataset 1, Zoom 2 (Whit Monday 2018)



Figure 29: Baseline Prediction for Dataset 1, Zoom 3 (Corpus Christi 2019)



Figure 30: Baseline Prediction for Dataset 1, Zoom 4 (29.07.2019 until 25.08.2019)

### 4.3.1.2 Artificial Neural Network

Table 3: Dataset 1 ANN Error Statistics						
	MAE	MSE	RMSE	CAE	RMSE	CAE
	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[%]	[%]
Full	0.33	0.214	0.462	11310	42	44
Zoom 1	0.256	0.113	0.336	369	48	51
Zoom 2	0.303	0.189	0.435	378	-6	7
Zoom 3	0.342	0.19	0.435	460	34	37
Zoom 4	0.266	0.112	0.335	689	20	22

A total of 41 ANN models have been tested on Dataset 1, with an overall mean RMSE of 0.559 and a mean absolute error of 13947.

The selected model showed the best prediction performance of ANN models trained on Dataset 1. It used 7 days as input and had 3 hidden layers, with 58 neurons each and deployed relu as activation function.

The prediction for 2019, shown in *Figure 31*, resembles the ground truth better than baseline, especially from July 2019. However, until July 2019, the model predicts many drops in consumption not occurring in the baseline.

Overall the model achieves an RMSE of 0.462 and an absolute error of 11310, providing improvements of 42% and 44% respectively.

*Figure 32* shows the ANN prediction of Zoom 1. Until March 11<sup>th</sup> the ground truth presents a weeky pattern, with consumption drops in the early morning hours and at weekends (weekends: March 2<sup>nd</sup> to March 3<sup>rd</sup> and March 8<sup>th</sup> to March 10<sup>th</sup>). The ANN model learned to approximate the weekly pattern, but starts to diverge from March 11<sup>th</sup>. The ANN model achieved an RMSE value of 0.336 and a absolute error of 369 compared to baseline. This is an improvement of 48% and 51%, respectively.

*Figure 33* depicts prediction and ground truth for Zoom 2, with the model accurately predicting the daily and weekly consumption patterns. Whit Monday 2018 does not impact the prediction in Zoom 2 (19.5.2019 - 20.5.2019). However, a consumption drop at night between March 20<sup>th</sup> and March 21<sup>st</sup> results in prediction inaccuracies, persisting until the end of March 21<sup>st</sup>. With the beginning of March 22<sup>nd</sup>, the prediction is again a good estimate for the ground truth. The reason for the inaccuracy lasting a bit more than 24 hours is to be found in the assumption, that, from midnight of a given day, the next 24 hours have to be predicted., limiting the algorithms capabilities to adapt to changes.

For Zoom 2 the ANN model achieves an RMSE value of 0.435 and a cumulative absolute error of 378, performing by 6% worse on the RMSE than baseline, but 7% better on CAE.

In Zoom 3, shown in *Figure 34*, the model roughly approximates the ground truth, but the intra-day consumption characteristics are different compared to Zoom 2, worsening the prediction performance. The ANN model accounts for Corpus Christi 2019 by reducing the predicted consumption level, but is too conservative in its prediction for the following bridging day. The ANN model achieves an RMSE value of



Figure 31: ANN Prediction for Dataset 1

0.435 and an cumulative absolute error of 460, representing an improvement of 34% and 37% compared to the baseline.

In Zoom 4, the ANN model follows the weekly consumption pattern of the ground truth and accounts for Assumption Day 2019 while bouncing back comparatively slow the day after. The ANN model achieves an RMSE value of 0.335 and an cumulative absolute error of 689, representing an improvement of 20% and 22%, respectively.



Figure 32: ANN Prediction for Dataset 1, Zoom 1 (01.03.2019 until 16.03.2019)



Figure 33: ANN Prediction for Dataset 1, Zoom 2 (Whit Monday 2018)



Figure 34: ANN Prediction for Dataset 1, Zoom 3 (Corpus Christi 2019)



Figure 35: ANN Prediction for Dataset 1, Zoom 4 (29.07.2019 until 25.08.2019)

## 4.3.1.3 Convolution Neural Network

Table 4: Dataset 1 CNN Error Statistics						
	MAE	MSE	RMSE	CAE	RMSE	CAE
	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[%]	[%]
Full	0.338	0.235	0.485	11686	39	42
Zoom 1	0.271	0.132	0.364	391	43	48
Zoom 2	0.31	0.226	0.476	387	-16	5
Zoom 3	0.386	0.24	0.49	519	26	29
Zoom 4	0.271	0.119	0.345	702	18	20

For Dataset 1, a total of 35 CNN models have been trained and tested, of which 26 achieved better results than baseline, with an overall mean RMSE of 0.907 and a mean absolute error of 26442.

The selected model showed the best prediction performance of all CNN models trained on Dataset 1. It used 4 hidden layers, with 39 neurons each a kernel size of 3, a pooling size of 5, 4 days as input and relu as activation function. *Table 4* lists the error statistics for the whole dataset ("full"), Zoom 1, Zoom 2, Zoom 3 and Zoom 4.

Figure 36 shows prediction and ground truth using the CNN model for the whole test data. Similar to Section 4.3.1.2, the model is predicting drops in electricity demand up to July 2019 that are not present in the ground turth. Overall, the CNN model performs slightely worse than the ANN model presented in Section 4.3.1.2 with an achieved RMSE value of 0.485 and an absolute error of 11686, representing an improvement of 39% and 42% respectively.

*Figure 37, Figure 38, Figure 39* and *Figure 39* show the graphs for Zoom 1, Zoom 2, Zoom 3 and Zoom 4, respectively.

Similar to the ANN model presented in *Section 4.3.1.2*, the model has learned the weekly pattern for the first half of Zoom 1. Starting from March 10<sup>th</sup>, the CNN model has difficulties to accurately predict the volatile energy consumption data.

In Zoom 2, the model is approximating the daily patterns of the first week and first weekend very well, is over estimating the consumption of March  $20^{th}$  and has, like the ANN model, a 24h delay before adapting to the dropped energy consumption of March  $21^{st}$ .

In Zoom 3, the CNN model is over-estimating the consumption for normal weekdays and Corpus Christi (March 20<sup>th</sup>), but is tremendously under-estimating the consumption for the bridge day (March 21<sup>st</sup>).

For Zoom 4, the CNN model is generally approximating the demand curve, however, compared to the ANN model, the CNN model is over-estimating many of the normal load peaks.

*Table 4* lists the performance metrics for the whole testset, Zoom 1, Zoom 2, Zoom 3 and Zoom 4.



Figure 36: CNN Prediction for Dataset 1



Figure 37: CNN Prediction for Dataset 1, Zoom 1 (01.03.2019 until 16.03.2019)



Figure 38: CNN Prediction for Dataset 1, Zoom 2 (Whit Monday 2018)



Figure 39: CNN Prediction for Dataset 1, Zoom 3 (Corpus Christi 2019)



Figure 40: CNN Prediction for Dataset 1, Zoom 4 (29.07.2019 until 25.08.2019)

	Table	5. Dataset	T LO I IVI EII	or Statistics		
	MAE [Wh/Wh]	MSE [Wh/Wh]	RMSE [Wh/Wh]	CAE [Wh/Wh]	RMSE [%]	CAE [%]
Full	0.318	0.195	0.441	10840	45	46
Zoom 1	0.274	0.127	0.357	395	44	48
Zoom 2	0.269	0.118	0.344	336	16	18
Zoom 3	0.295	0.139	0.373	397	44	46
Zoom 4	0.267	0.108	0.328	693	22	21

Table 5: Dataset 1 LSTM Error Statistics

A total of 9 LSTM models have been tested on Dataset 1, achieving a mean RMSE of 0.469, a mean absolute error of 11650 and every model performed better than the Baseline. The LSTM training process took on day (24h) per model, for Dataset 1, limiting the number of trained models.

The selected LSTM model showed the best prediction performance of LSTM models trained on Dataset 1. It used 3 hidden layers, with 94 neurons each, *relu* as activation function and utilized 9 days of input data.

Figure 41 depicts prediction and ground truth for Dataset 1, using the LSTM model for the whole test dataset, showing that the model has a tendency of over estimating. Further, the LSTM model is forecasting drops in energy demand not present in ground truth data, similar to the ANN an CNN models. Overall, the LSTM model achieves an RMSE of 0.441 and a cumulative absolute error of 10840, achieving an improvement of 45% and 56% compared to the Baseline.

*Figure 42, Figure 43, Figure 44* and *Figure 45* show the graphs for Zoom 1, Zoom 2, Zoom 3 and Zoom 4.

Similar to the ANN and CNN models, evaluated in *Section 4.3.1.2* and *Section 4.3.1.3*, the model has learned the weekly pattern for the first half of Zoom 1 and produces error, when the ground truth experiences a negative peak on Match  $10^{\text{th}}$ . The LSTM prediction requires slightly above 24h to adapt to the change in electricity demand, due to the prediction precondition introduced in *Section 4.3.1.2*. On Zoom 1, the model achieved an RMSE of 0.357 and an cumulative absolute error of 395, improving by 44% and 48%, respectively.

In Zoom 2, the model is anticipating the load demand for the work week between March  $13^{\text{th}}$  and March  $18^{\text{th}}$ , but it is under-estimating the demand compared to the ANN and CNN model. The load peak of March  $20^{\text{th}}$  is predicted with less error compared to the CNN model and the following predicted peak (March  $21^{\text{st}}$ ) is smaller than for the ANN and CNN model. Further, the LSTM model is underestimating the demand for the period from March  $22^{\text{nd}}$ , compared to *Figure 33* and *Figure 38*. The LSTM model achieved an RMSE of 0.344 and a cumulative absolute error of 336, improving by 16% and 18% compared to the Baseline.

In Zoom 3, the LSTM model is producing less error during Corpus Christi 2019 (June  $20^{th}$ ) and bounces back faster for the bridging day (June  $21^{st}$ ), compared to the ANN and CNN model. The LSTM model achieved an RMSE of 0.373 and a



Figure 41: LSTM Prediction for Dataset 1

cumulative absolute error of 397 for Zoom 3, improving by 44% and 46% compared to the Baseline.

Assessing Zoom 4, the LSTM mdoel is generally less over-predicting and more often under-predicting, compared to the ANN and CNN model. It achieves an RMSE of 0.328 and a cumulative absolute error of 693, improving by 22% and 21% compared to the Baseline.

## 4.3.1.5 Summary

Dataset 1 was provided by a pharmaceutical packaging manufacturer, with a high volatility in load demand. The bes prediction results were achieved by the LSTM model, reducing the error by 45% for the RMSE and 46% for the cumulative absolute error, compared to baseline. Performing worst was the CNN model, with an improvement of 39% and 42%, respectively. The ANN model achieved an improvement of 42% (RMSE) and 44% (CAE), achieving just 3% or 4% worse results, than the LSTM model. With on hour average training time, the ANN models have been significantly cheaper to train than the LSTM models, requiring an average of 24h each on Dataset 1. Depending on the required retraining frequency, it may be advisable to use the cheaper ANN instead of the more accurate LSTM model.



Figure 42: LSTM Prediction for Dataset 1, Zoom 1 (01.03.2019 until 16.03.2019)



Figure 43: LSTM Prediction for Dataset 1, Zoom 2 (Whit Monday 2018)



Figure 44: LSTM Prediction for Dataset 1, Zoom 3 (Corpus Christi 2019)



Figure 45: LSTM Prediction for Dataset 1, Zoom 4 (29.07.2019 until 25.08.2019)

### 4.3.2 Processing Dataset 2

Following, the test data of Dataset 2 is predicted using the Baseline and the best performing neural network model, convolution neural network model and long-short term memory model.

#### 4.3.2.1 Baseline

Ta	Table 6: Dataset 2 Baseline Error Statistics						
	MAE [Wh/Wh]	MSE [Wh/Wh]	RMSE [Wh/Wh]	CAE [Wh/Wh]			
Full	0.141	0.041	0.202	3693			
Zoom 1	0.178	0.071	0.266	257			
Zoom 2	0.148	0.038	0.196	185			
Zoom 3	0.156	0.047	0.217	209			
Zoom 4	0.134	0.040	0.200	349			

*Figure 46* shows the Baseline prediction, using the baseline algorithm introduced in *Section 3.2*, for all test data of Dataset 2. The weekly demand cycles are clearly recognisable in the full plot. *Figure 46* suggests that the baseline is overestimating the demand from June 2019 until October 2019. Overall, the Baseline achieved an RMSE of 0.202 and a cumulative absolute error of 3693 on Dataset 2. *Figure 47*, *Figure 48*, *Figure 49* and *Figure 50* are depicting the baseline predictions for Zoom 1, Zoom 2, Zoom 3 and Zoom 4.

For Zoom 1, the baseline is predicting a steep drop in Friday March 8<sup>th</sup>, producing significant error. In Zoom 2, the historic data used for the Baseline accurately predicts the energy demand of the test data. The holiday compensation for Whit Monday (March 20<sup>th</sup>) is clearly recognisable.

Looking at Zoom 3, the holiday adjustment for Corpus Christi 2019 can be detected easily and the bridgeday prediction (March  $21^{st}$ ) is predicting the amplitude correctly. For Zoom 3, the Baseline achieves an RMSE of 0.217 and a cumulative absolute error of 209.

In Zoom 4, the adjustments for Assumption Day 2018 and 2019 are clearly recognisable on March  $14^{th}$  and March  $15^{th}$ , respectively. The Baseline achieves an RMSE of 0.2 and a cumulative absolute error of 249 for Zoom 4.



Figure 46: Baseline Prediction for Dataset 2



Figure 47: Baseline Prediction for Dataset 2, Zoom 1 (01.03.2019 until 16.03.2019)



Figure 48: Baseline Prediction for Dataset 2, Zoom 2 (Whit Monday 2018)



Figure 49: Baseline Prediction for Dataset 2, Zoom 3 (Corpus Christi 2019)



Figure 50: Baseline Prediction for Dataset 2, Zoom 4 (29.07.2019 until 25.08.2019)

### 4.3.2.2 Artificial Neural Network

Table 7: Dataset 2 ANN Error Statistics						
	MAE	MSE	RMSE	CAE	RMSE	CAE
	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[%]	[%]
Full	0.112	0.023	0.152	2866	25	22
Zoom 1	0.126	0.03	0.174	181	35	30
Zoom 2	0.11	0.02	0.142	137	28	26
Zoom 3	0.143	0.036	0.191	192	12	8
Zoom 4	0.102	0.018	0.134	265	33	24

For Dataset 2, a total of 30 ANN models have been trained and tested. 11 models performed better than baseline, with an overall RMSE of 0.283 and a cumulative absolute error of 5728. The selected model achieved an RMSE of 0.152 and a cumulative absolute error of 2866 on the test data. This is an improvement of 25% and 22%, compared to the baseline.

*Figure 51* shows the prediction of the test data for Dataset 2, using the selected ANN model. *Figure 52, Figure 53, Figure 54* and *Figure 55* depict prediction and ground truth for Zoom 1, Zoom 2, Zoom 3 and Zoom 4.

When comparing Zoom 1 and Zoom 2, it can be seen, that the ANN model learned a specific pattern, approximating the actual consumption pattern. In Zoom 1, the time at the beginning of March 4<sup>th</sup> and March 11<sup>th</sup> produces a large error, not occurring in Zoom 3, indicating that the model learned a "generalized" pattern that is interrupted by irregularities. In Zoom 3, this "generalized" pattern is interrupted by Corpus Christi 2019, indicating that the model can cope with calendric variation.

The ANN model has learned to predict Fridays as work days, with slightly reduced load (e.g. May 17<sup>th</sup> or May 24<sup>th</sup> in Zoom 2). However, Fridays are not necessarily following the learned, "generalized" pattern (for example Friday March 15<sup>th</sup> in Zoom 1), deteriorating the prediction performance. The reason for the demand divergence can probably be found in the plants order situation or operative planning, not providing a learnable signal. Without a learnable signal, the algorithm is not able to discriminate between normal and reduced load Fridays.

The ANN model is accurately predicting the consumption drop, inflicted by Assumption Day 2019 (August 15<sup>th</sup>), but it is not expecting a bridge day with reduced demand on August 16<sup>th</sup>, introducing error by significantly over-estimating the load demand. This error could be circumvented by adding plant internal planning information to the algorithms input.

For Zoom 1, the algorithm achieved an RMSE of 0.174 and a cumulative absolute error of 181, improving by 35% and 30% compared to the baseline. For Zoom 2, an RMSE of 0.142 and a cumulative absolute error of 137 was achieved, improving the prediction by 28% and 26% respectively. In Zoom 3, the ANN model is performing worse than in Zoom 1, Zoom 2 or Zoom 4, achieving an RMSE of 0.191 and a cumulative absolute error of 192, improving the baseline by just 12% and 8%.

Lastly, the ANN model was able to improve the RMSE by 33% and the cumulative absolute error by 24% for Zoom 4, compared to the baseline, achieving an RMSE value



of 0.134 and a cumulative absolute error of 265.





Figure 52: ANN Prediction for Dataset 2, Zoom 1 (01.03.2019 until 16.03.2019)



Figure 53: ANN Prediction for Dataset 2, Zoom 2 (Whit Monday 2018)



Figure 54: ANN Prediction for Dataset 2, Zoom 3 (Corpus Christi 2019)



Figure 55: ANN Prediction for Dataset 2, Zoom 4 (29.07.2019 until 25.08.2019)

## 4.3.2.3 Convolution Neural Network

Table 8: Dataset 2 CNN Error Statistics						
	MAE	MSE	RMSE	CAE	RMSE	CAE
	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[%]	[%]
Full	0.113	0.023	0.151	2872	25	22
Zoom 1	0.125	0.026	0.163	179	39	30
Zoom 2	0.095	0.016	0.126	119	36	36
Zoom 3	0.166	0.048	0.22	224	-1	-7
Zoom 4	0.105	0.021	0.146	272	27	22

A total of 35 CNN models have been trained on Dataset 2, of which 12 performed better than the Baseline established in *Section 4.3.2.1*. All CNN models combined achieved an overall mean RMSE of 0.567 and a mean cumulative error of 18404. The selected model is comprised of 6 hidden layers with 80 neurons each, uses a kernel size of 3 and a pooling size of 4, relu as activation function and 8 days of input data.

Figure 56 shows the prediction and ground truth of Dataset 2. The selected CNN model achieved an RMSE value of 0.151, improving the prediction accuracy by 25% compared to the Baseline and a cumulative absolute error of 2872, improving the prediction accuracy by 22%.

*Figure 57, Figure 58, Figure 59* and *Figure 60* depict prediction, ground truth and error for Zoom 1, Zoom 2, Zoom 3 and Zoom 4.

The predicted demand pattern shown in Zoom 1 indicates, that the model learned a general regression function, smoothing the load patterns. Due to this smoothing property, the model performs bad in predicting steep demand changes, causing the prediction error to increase each Monday (e.g. March 4<sup>th</sup> or March 11<sup>th</sup> in Zoom 1). The absolute errors for work days are comparable with the absolute errors produced by the ANN model, levelling around 0.2 for both.

Generally, the CNN model has difficulties to accurately predict the demand for the days before and after Corpus Christi 2019, generating absolute errors of about 0.5, exceeding the work week error of Zoom 1 twice.

In Zoom 4, the CNN model is achieving results comparable to the ANN model, producing absolute errors between 0.2 and 0.25 for normal work weeks. However, the bridge day after Mary Assumption (August 16<sup>th</sup>) is significantly overestimated, generating absolute errors of 0.75 and more, compared to the ANN model producing absolute errors of 0.4 - 0.5 in *Figure 55*.

The CNN model achieved an RMSE of 0.163 and a cummulative absolute error of 179, for Zoom 1, improving by 39% and 30%. For Zoom 2, it achieved an RMSE of 0.126, improving by 36% and a cumulative absolute error of 119, improving by 36%. On Zoom 3, the model achieved worse results compared to the Baseline, scoring an RMSE of 0.22 and a cumulative absolute error of 224. For Zoom 4, the model achieved a improvement of 27% and 22% respectively, producing an RMSE value of 0.146 and a cumulative absolute error of 272.



Figure 56: CNN Prediction for Dataset 2



Figure 57: CNN Prediction for Dataset 2, Zoom 1 (01.03.2019 until 16.03.2019)


Figure 58: CNN Prediction for Dataset 2, Zoom 2 (Whit Monday 2018)



Figure 59: CNN Prediction for Dataset 2, Zoom 3 (Corpus Christi 2019)



Figure 60: CNN Prediction for Dataset 2, Zoom 4 (29.07.2019 until 25.08.2019)

	Table	<u>9. Dataset i</u>		<u>or statistics</u>		
	MAE	MSE	RMSE	CAE	RMSE	CAE
	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[%]	[%]
Full	0.103	0.022	0.148	2671	27	28
Zoom 1	0.117	0.029	0.17	168	36	35
Zoom 2	0.105	0.019	0.138	132	30	28
Zoom 3	0.13	0.037	0.191	174	12	17
Zoom 4	0.105	0.027	0.165	273	18	22

Table 9: Dataset 2 LSTM Error Statistics

For Dataset 2, a total of 30 LSTM models have been trained and tested, and 22 models performed better than the Baseline, with an overall mean RMSE of 0.188 and a mean cumulative absolute error of 3217. The selected model uses one hidden layer, with 73 neurons each, facilitated a tanh activation function and used three days as input data. The model achieved an RMSE of 0.148 and a cumulative absolute error of 2671 on the test data, improving the prediction by 27% and 28%, respectively.

Figure 61 shows the LSTM prediction and ground truth for Dataset 2, indicating that the majority of absolute errors are peaking between 0.25 and 0.5.

*Figure 62, Figure 63, Figure 64* and *Figure 65* depict prediction, ground truth and error for Zoom 1, Zoom 2, Zoom 3 and Zoom 4.

Comparing Zoom 1 to Zoom 4 indicates, that the selected LSTM model is generally under-estimating the load demand for Mondays and that the model has learned to condense the demand pattern to a regression function, generally ignoring intradays patterns. The LSTM model has the same difficulties to predict low-load Fridays (March 15<sup>th</sup> in Zoom 1) correctly, as the ANN and CNN model, supporting the assumption that signals are missing to correctly predict Fridays load demand. Additionally, the LSTM model is equally bad in predicting the bridge day (August 16<sup>th</sup>) of Zoom 4.

## 4.3.2.5 Summary

Dataset 2 was provided by a paper manufacturing plant. The demand pattern is repetitive, with daily and weekly variations clearly identifiable. The ANN and CNN model are performing equally well, reducing the error by 25% (RMSE) or 22% (cumulative absolute error). The best results are achieved by the LSTM mode, improving prediction performance by 27% (RMSE) or 28% (CAE) compared to the Baseline. Besides intra-day variation, the most significant error is caused by unpredictable load patterns on Fridays and unexpected load reduction on bridge days. When implementing LSTM for Company B, it is suggested to provide internal planing information as algorithm input to eliminate prediction inaccuracies for Fridays, bridge days and intra-day deviations.



Figure 61: LSTM Prediction for Dataset 2



Figure 62: LSTM Prediction for Dataset 2, Zoom 1 (01.03.2019 until 16.03.2019)



Figure 63: LSTM Prediction for Dataset 2, Zoom 2 (Whit Monday 2018)



Figure 64: LSTM Prediction for Dataset 2, Zoom 3 (Corpus Christi 2019)



Figure 65: LSTM Prediction for Dataset 2, Zoom 4 (29.07.2019 until 25.08.2019)

#### 4.3.3 Processing Dataset 3

## 4.3.3.1 Baseline

	MAE [Wh/Wh]	MSE [Wh/Wh]	RMSE [Wh/Wh]	CAE [Wh/Wh]
Full	0.203	0.095	0.309	7128
Zoom 1	0.156	0.037	0.193	224
Zoom 2	0.210	0.086	0.293	262
Zoom 3	0.233	0.118	0.343	313
Zoom 4	0.162	0.064	0.253	420

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Figure 66 shows the Baseline prediction for Dataset 3 using the Baseline algorithm introduced in Section 3.2 for the entire test set, indicating a repetitive load demand pattern, with three maintenance or holiday periods. Overall, the Baseline achieved an RMSE of 0.309 and a cumulative absolute error of 7128.

*Figure 67, Figure 68, Figure 69* and *Figure 70* depict prediction, ground truth and error for Zoom 1, Zoom 2, Zoom 3 and Zoom 4.

Zoom 1 to Zoom 4 reinforce the assumption of highly repetitive demand patterns, suggesting limited improvement potential. In Zoom 2, the baseline algorithm is generating error by replacing Whit Monday 2018 with the mean consumption of a workday. The drop of Corpus Christi 2019 (June 20<sup>th</sup>) is accounted for by using the mean consumption of off-days as forecast. However, the bridge day after Corpus Christi 2019 (June 21<sup>st</sup>) has been a normal workday in 2018, resulting in a false prediction.

Zoom 4 shows a two week holiday/maintenance period of Company C. The data of the previous year is accurately predicting the consumption for the first week. For the second week, the Baseline Algorithm is generating an error by replacing Assumption Day 2018 (August 14<sup>th</sup> in *Figure 70*) with the workday mean and Assumption Day 2019 (August 15<sup>th</sup> in *Figure 70*) with the off-day mean, both forecasting higher loads than necessary for the holiday period. *Table 10* lists the performance statistics for the Baseline of Dataset 3.



Figure 66: Baseline Prediction for Dataset 3



Figure 67: Baseline Prediction for Dataset 3, Zoom 1 (01.03.2019 until 16.03.2019)



Figure 68: Baseline Prediction for Dataset 3, Zoom 2 (Whit Monday 2018)



Figure 69: Baseline Prediction for Dataset 3, Zoom 3 (Corpus Christi 2019)



Figure 70: Baseline Prediction for Dataset 3, Zoom 4 (29.07.2019 until 25.08.2019)

### 4.3.3.2 Artificial Neural Network

Table 11: Dataset 3 ANN Error Statistics						
	MAE	MSE	RMSE	CAE	RMSE	CAE
	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[%]	[%]
Full	0.21	0.098	0.313	8168	-1	-15
Zoom 1	0.219	0.094	0.306	315	-58	-40
Zoom 2	0.21	0.088	0.296	262	-1	0
Zoom 3	0.22	0.102	0.319	296	7	5
Zoom 4	0.186	0.111	0.333	482	-32	-15

For Dataset 3, a total of 60 models have been trained, of which none has performed better than Baseline. The selected model has performed best among the trained models, achieving an RMSE of 0.313 and a cumulative absolute error of 8168, performing 1% and 15% worse then Baseline.

*Figure 71* shows the overall ground truth, predicted load demand and the absolute errors. *Figure 72, Figure 73, Figure 74, and Figure 75* show prediction, ground truth and absolute errors for Zoom 1, Zoom2, Zoom 3 and Zoom 4.

The model has learned a regressive function to predict the future load demand, but as the demand patterns of 2018 and 2019 are highly recurring, the learned regression curve is performing significantly worse than the Baseline, achieving an RMSE of 0.306 and a cumulative absolute error of 315, deteriorating the performance by 58% and 40% compared to Baseline.

Only for Zoom 3, the ANN model is able to outperform the Baseline by 7% for the RMSE and 5% for the cumulative absolute error, as it is good in predicting the reduced load demand for the bridge day. The ANN model has learned to quickly identify holiday/maintenance periods completely adjusting to the drop in load demand after an adoption period of 24h, as shown in Zoom 4. However, while adapting to the holiday/maintenance mode quickly, the model is not anticipating the return no normal demand behaviour requiring another adaptation period of 24h. The performance metrics for the whole testset, Zoom 1, Zoom 2, Zoom 3 and Zoom 4 are listed in *Table 11*.



Figure 71: ANN Prediction for Dataset 3



Figure 72: ANN Prediction for Dataset 3, Zoom 1 (01.03.2019 until 16.03.2019)



Figure 73: ANN Prediction for Dataset 3, Zoom 2 (Whit Monday 2018)



Figure 74: ANN Prediction for Dataset 3, Zoom 3 (Corpus Christi 2019)



Figure 75: ANN Prediction for Dataset 3, Zoom 4 (29.07.2019 until 25.08.2019)

## 4.3.3.3 Convolution Neural Network

Table 12: Dataset 3 CNN Error Statistics						
	MAE	MSE	RMSE	CAE	RMSE	CAE
	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[%]	[%]
Full	0.161	0.055	0.234	6516	24	9
Zoom 1	0.173	0.053	0.231	249	-20	-11
Zoom 2	0.149	0.039	0.198	187	32	29
Zoom 3	0.13	0.033	0.18	174	48	44
Zoom 4	0.192	0.09	0.299	499	-18	-19

A total of 35 CNN models have been trained and tested on Dataset 3, achieving a mean RMSE of 0.567 and a mean cumulative absolute error of 18404. 12 models performed better than the Baseline. The selected CNN model was built using one hidden layer, 65 neurons, a kernel size of 3 and a pooling size of 4, utilizing tanh as activation function and four days as input data. The selected CNN model achieved an RMSE of 0.234 and a cumulative absolute error of 6516 on the whole test set, improving by 24% and 9% compared to baseline.

*Figure 76* shows the overall ground truth, predicted load demand and the absolute errors. *Figure 77, Figure 78, Figure 79, and Figure 80* show prediction, ground truth and absolute errors for Zoom 1, Zoom2, Zoom 3 and Zoom 4.

Comparing the weekday predictions for Zoom 1, Zoom 2 and Zoom 4, it is obvious that the model has learned different patterns, for different load conditions (higher load demand predicted for Mondays in Zoom 1 and equal to lower load demand predicted for Mondays in Zoom 2 and Zoom 4). The model is accurately predicting Corpus Christi 2019 (June 20<sup>th</sup>) and is also performing well in predicting the bridge day after Corpus Christi 2019 (June 21<sup>st</sup>). In Zoom 1, the model seems to have issues predicting the intra-day demand accurately and in Zoom 4, the model had difficulties reducing the predicted load to zero for the holiday/maintenance period.

The CNN model is performing worse than the Baseline for Zoom 1 and Zoom 4, scoring RMSEs of 0.053 and 0.09 and cumulative absolute errors of 249 and 499.

Table 12 lists the performance metrics for the selected CNN model.



Figure 76: CNN Prediction for Dataset 3



Figure 77: CNN Prediction for Dataset 3, Zoom 1 (01.03.2019 until 16.03.2019)



Figure 78: CNN Prediction for Dataset 3, Zoom 2 (Whit Monday 2018)



Figure 79: CNN Prediction for Dataset 3, Zoom 3 (Corpus Christi 2019)



Figure 80: CNN Prediction for Dataset 3, Zoom 4 (29.07.2019 until 25.08.2019)

	MAE	MSE	RMSE	CAE	RMSE	CAE
	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[Wh/Wh]	[%]	[%]
Full	0.155	0.053	0.23	6272	26	12
Zoom 1	0.132	0.029	0.17	190	12	15
Zoom 2	0.149	0.04	0.2	186	32	29
Zoom 3	0.125	0.029	0.171	168	50	46
Zoom 4	0.156	0.08	0.282	404	-12	4

Table 13: Dataset 3 LSTM Error Statistics

A total of 29 LSTM models have been trained and tested on Dataset 3, with 27 performing better than the Baseline. Together, the models achieved a mean RMSE of 0.273 and a mean cumulative absolute error of 7217. The selected model uses a relu activation function, three days as input data and five hidden layers, with 41 neurons each.

Overall, the model achieved an RMSE of 0.23 and a cumulative absolute error of 6272, improving by 26% and 12%. Unlike to the CNN model, the LSTM model predicts very similar patterns for normal work weeks, predicting relatively constant demand levels across working days. However, the model is still outperforming the Baseline for Zoom 1, Zoom 2 and Zoom 3. Similar to the ANN and CNN model, the LSTM model has difficulties predicting if a Monday is the beginning of a holiday/maintenance period, but is able to adapt to the drop in energy demand within 24h. Having those issues, the LSTM model is achieving an RMSE of 0.282 and a cumulative absolute error of 404, performing by 12% worse than the Baseline for the RMSE. This drop in prediction performance can be improved by providing company internal planning information to the model input data.

Table 13 lists the performance metrics for the selected LSTM model.

## 4.3.3.5 Summary

Dataset 3 was provided by a utility company and the true origin of the dataset is unknown. The demand pattern is highly recurring, with little volatility and the company is scheduling fixed holiday/maintenance periods. On Dataset 3, the CNN and LSTM models are performing better than baseline, with the LSTM outperforming the CNN model by 2% for the RMSE and 3% for the cumulative absolute error. Overall it is possible to reduce the prediction error by 26% for the RMSE and 12% for the cumulative absolute error, using LSTM.

All algorithms had difficulties predicting holiday/maintenance periods. Providing internal planning information as algorithm input could significantly strengthen the prediction performance.



Figure 81: LSTM Prediction for Dataset 3



Figure 82: LSTM Prediction for Dataset 3, Zoom 1 (01.03.2019 until 16.03.2019)



Figure 83: LSTM Prediction for Dataset 3, Zoom 2 (Whit Monday 2018)



Figure 84: LSTM Prediction for Dataset 3, Zoom 3 (Corpus Christi 2019)



Figure 85: LSTM Prediction for Dataset 3, Zoom 4 (29.07.2019 until 25.08.2019)

## 5 Conclusion

In the context of this master thesis, three different deep learning algorithms were tested for their ability to predict industrial electricity demand one day in advance with a consumption accuracy of 15 minutes. Due to their widespread use, Artificial Neural Networks (ANN), Convolution Neural Networks (CNN) and Long-Short Term Memory Networks (LSTM) were selected for the experiments. The baseline algorithm deployed is the method used by Company B and Company C in practice, which assumes last year's consumption as a prediction for future consumption. The experiments were conducted on three industrial data sets, each of which has different consumption characteristics and covers at least a period of one year and nine months up to a period of seven years. Before the baseline algorithms or deep learning algorithms could be applied to the data, the datasets were first manually inspected to understand their properties and then unified into a coherent data structure (pre-processing). Subsequently, a separate baseline was calculated for each data source in order to be able to decide on the performance of the predictions during the deep learning experiments. To conduct the experiments efficiently, all Deep Learning specific activities were combined in a Deep Learning Pipeline, in which the power consumption data was extended by date and holiday information, the dataset was divided into a training and test set and the Deep Learning models were trained, evaluated and optimized. Normalized data were used for the training process and, to ensure comparability between the datasets, standardized data was used for the documentation within the scope of this writing.

To find the best hyperparameter configuration for each dataset and model, more than 200 models were trained and evaluated. For every dataset, LSTM models gave better results than the baseline, ANN and CNN models. The ANN and CNN models alternate in 2nd and 3rd place in terms of prediction accuracy. The level of improvement in prediction accuracy varies, depending on the consumption volatility of the dataset studied, between approximately 20% and 45% per model, compared to the baseline. When demand volatility is high, the consumption data from the previous year is a poor approximation of actual demand and this leads to a high divergence between predicted and actual demand. Dataset 1 has the highest demand volatility, and the selected LSTM model achieved a 45% RMSE improvement. The ANN model was not significantly worse, with a 42% RMSE improvement. The CNN model was "only" able to achieve an RMSE improvement of 39%. Applied to Dataset 2, the best LSTM model achieved an RMSE improvement of 27% while both the ANN model and the CNN model achieved an RMSE improvement of 25%. Dataset 3 has the highest percentage of recurring consumption patterns, so the baseline is already a passable approximation to the actual consumption. With the LSTM model selected for Dataset 3, an RMSE improvement of 26% was achieved. In this case, the CNN model selected for Dataset 3 came second, with an RMSE improvement of 24%, and none of the trained ANN models achieved better results than the baseline. Comparing the prediction improvement of the LSTM models with the second placed models, the LSTM models achieve an improvement of only 2-3%. Since LSTM models are much more expensive to train than ANN or CNN models, due to the complexity of the models, it may be preferable to use ANN or CNN models despite their poorer performance compared to LSTM models in applications requiring frequent re-training, for example when new consumption data is to be incorporated into the model quickly. If frequent re-training is not necessary, LSTM models should be chosen over ANN or CNN models.

On all datasets the algorithms had to cope with changes in demand patterns, due to bridge days, changes in production processes or order situation and unpredictable holiday/maintenance periods. Overall, the algorithms managed to adapt their forecasts quickly to a changing demand situation.

As a next step, the partner companies will be informed about the achieved results. Furthermore, the Deep Learning Pipeline allows to easily test more complex model architectures, further generalization methods or changes of the used input data.

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