Acoustic Topology Optimization in openCFS

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Solid Isotropic Material with Penalization (SIMP)

$$\begin{split} & \text{given} \quad \mathbf{f} \in \mathbb{C}^{N \cdot \mathsf{DOF}} \\ & \text{find} \quad \min_{\rho} J(\mathbf{u}) = \min_{\rho} \mathbf{u}^\mathsf{T} \mathbf{f} \in \mathbb{R}^+ \\ & \text{s.t.} \quad \widetilde{\mathbf{K}} \mathbf{u} = \mathbf{f} \\ & \quad \widetilde{\mathbf{K}} = \bigwedge_{e=1}^E \bar{\rho}_e^\rho \mathbf{K}_e \\ & \quad \bar{\rho}_e := \frac{\sum_{\eta=1}^E w(\mathbf{x}_\eta - \mathbf{x}_e) \rho_\eta}{w(\mathbf{x}_\eta - \mathbf{x}_e)} \qquad \qquad \forall \ 1 \leqslant e \leqslant E \\ & \quad w(d) = \max(0, R - |d|) \\ & \quad \rho_e \in [\rho_{\mathsf{min}}, 1] \qquad \qquad \forall \ 1 \leqslant e \leqslant E \end{split}$$

Recap: Sensitivity and Constraints



For the general compliance problem, the sensitivity is directly computed with the adjoined method as

$$\frac{\partial J}{\partial \rho_e} = -\mathbf{u}^{\mathsf{T}} \frac{\partial \widetilde{\mathbf{K}}}{\partial \rho_e} \mathbf{u} \qquad \forall \ 1 \leqslant e \leqslant E \ .$$

Additionally, we can add constraints for the optimization process e.g.

$$\frac{1}{E}\sum_{e=1}^{E}\bar{\rho}_{e}(\rho)\leqslant V^{*}$$

as volume constraint.

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Recap: Optimize



- init Set initial pseudo densities $\rho_e^{(0)} \quad \forall \ 1 \leqslant e \leqslant E$
 - 1 Apply filtering $\bar{\rho}_e := \frac{\sum_{\eta=1}^E w(r) \rho_{\eta}^{(i)}}{w(r)}$
 - 2 Penalize $\widetilde{\mathbf{K}} = \bigwedge_{e=1}^{E} \bar{\rho}_{e}^{p} \mathbf{K}_{e}$
 - 3 Solve FEM problem $\mathbf{K}\mathbf{u} = \mathbf{f}$ to obtain \mathbf{u}
 - 4 Check convergence (e.g. by evaluating cost function)
 - 5 Optimizer computes new pseudo densities $\rho_e^{(i+1)}$ from sensitivities and constraints

We quit the iteration at specified convergence criteria (e.g. relative change in cost function).

Acoustic Cost Functions



Squared pressure at selected DOFs (dynamicOutput)

$$J = \mathbf{p}^{\mathsf{T}} \mathbf{L} \mathbf{p}^{*}$$
 $rac{\partial J}{\partial
ho_{e}} = 2 \operatorname{Re} \left\{ \lambda^{\mathsf{T}} rac{\partial \widetilde{\mathbf{S}}}{\partial
ho_{e}} \mathbf{p}
ight\}$ s.t. $\widetilde{\mathbf{S}}^{\mathsf{T}} \lambda = -\mathbf{L} \mathbf{p}^{*}$

- p complex acoustic pressure
- L selector matrix
- s parameterized system matrix
- λ adjoined solution
- p₁ complex incident wave amplitude (at selected DOFs)

Squared reflected pressure at selected DOFs (reflectedWave)

$$J = (\mathbf{p} - \rho_l)^{\mathsf{T}} \mathbf{L} (\mathbf{p} - \rho_l)^*$$
$$\frac{\partial J}{\partial \rho_e} = 2 \operatorname{Re} \left\{ \lambda^{\mathsf{T}} \frac{\partial \widetilde{\mathbf{S}}}{\partial \rho_e} (\mathbf{p} - \rho_l) \right\}$$
s.t. $\widetilde{\mathbf{S}}^{\mathsf{T}} \lambda = -\mathbf{L} (\mathbf{p} - \rho_l)^*$

Acoustic Topology Optimization



Dynamic SIM(P) for the acoustic pressure formulation (for single frequency ω)

$$\begin{split} & \text{given} \quad \mathbf{f} \in \mathbb{C}^N \\ & \text{find} \quad \min_{\rho} J(\mathbf{p}) \in \mathbb{R}^+ \\ & \text{s.t.} \quad \widetilde{\mathbf{S}} \mathbf{p} = \mathbf{f} \\ & \quad \widetilde{\mathbf{S}} = \bigwedge_{e=1}^E \bar{\rho}_e (\mathbf{K}_e - \frac{\omega^2}{c_0^2} \mathbf{M}_e) \\ & \quad \bar{\rho}_e := \frac{\sum_{\eta=1}^E w(\mathbf{x}_\eta - \mathbf{x}_e) \rho_\eta}{w(\mathbf{x}_\eta - \mathbf{x}_e)} \qquad \qquad \forall \ 1 \leqslant e \leqslant E \\ & \quad w(d) = \max(0, R - |d|) \\ & \quad \rho_e \in [\rho_{\min}, 1] \qquad \qquad \forall \ 1 \leqslant e \leqslant E \end{split}$$

Multifrequency



In openCFS we have two ways to optimize for multiple frequencies.

Superposition (weighted average)

$$\begin{split} & \text{given} \quad \mathbf{f}_{\omega 1}, \mathbf{f}_{\omega 2} \\ & \text{find} \quad \min_{\rho} \frac{1}{2} J(\mathbf{p}_{\omega 1}) + \frac{1}{2} J(\mathbf{p}_{\omega 2}) \\ & \text{s.t.} \quad \widetilde{\mathbf{S}}_{\omega 1} \mathbf{p}_{\omega 1} = \mathbf{f}_{\omega 1} \\ & \quad \widetilde{\mathbf{S}}_{\omega 2} \mathbf{p}_{\omega 2} = \mathbf{f}_{\omega 2} \\ & \quad \dots \end{split}$$

min/max problem (slack formulation)

given
$$\mathbf{f}_{\omega 1}, \mathbf{f}_{\omega 2}$$

find $\min_{\rho} \alpha$
s.t. $\widetilde{\mathbf{S}}_{\omega 1} \mathbf{p}_{\omega 1} = \mathbf{f}_{\omega 1}$
 $\widetilde{\mathbf{S}}_{\omega 2} \mathbf{p}_{\omega 2} = \mathbf{f}_{\omega 2}$
 $J(\mathbf{p}_{\omega 1}) \leqslant \alpha$
 $J(\mathbf{p}_{\omega 2}) \leqslant \alpha$
 \dots
 $\alpha \in [0, \infty)$

Advanced Filtering



Projection: Apply a continuous Heaviside function to the density filtered field $H_{\beta}(\bar{\rho})$ prior penalization.

$$H_{\beta}(\bar{\rho}) = \frac{\tanh(\beta\eta) + \tanh(\beta(\bar{\rho} - \eta))}{\tanh(\beta\eta) + \tanh(\beta(1 - \eta))}$$

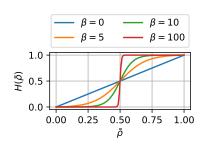
Robust: Solve three systems per iteration, with three Heaviside filter settings.

$$\eta_e < 0.5$$
 erode

$$\eta_d > 0.5$$
 dilate

$$\eta_i = 0.5$$
 intermediate

Shape Mapping: Parameterized curve shapes that are mapped to the density field.



$$\eta_e = 0.2$$

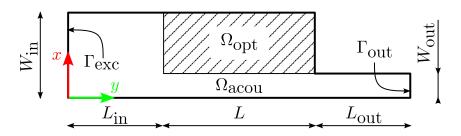
$$\eta_i = 0.5$$

 $\eta_d = 0.8$



Problem Statement





Goal: Maximize transmission between Γ_{in} and Γ_{out} .

$$L_{\rm in} = 0.1 \, {\rm m}$$

$$W_{\rm in} = 0.025 \, {\rm m}$$

$$L = 0.05 \, \text{m}$$

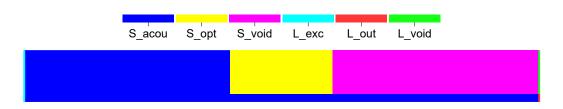
$$W_{\text{in}} = 0.025 \,\text{m}$$
 $W_{\text{out}} = 0.004 \,\text{m}$

$$L_{\rm out} = 0.1 \, \rm m$$

$$\omega \in [1000\,\text{Hz}, 2000\,\text{Hz}]$$

Mesh Generation





Uniform grid with rectangular quadrilateral elements, created using the Python mesh_tool module.

- Oreate uniform grid with mesh_tool.create_2d_mesh()
- 2 Assign elements to regions
- 3 Create line elements and assign to surface regions
- 4 Assign nodes to nodesets
- 5 Export mesh file with mesh_tool.write_ansys_mesh()

Optimization Setup XML

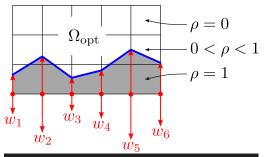


```
<costFunction type="reflectedWave" task="minimize" multiple excitation="true">
    <stopping queue="5" value="0.001" type="relativeCostChange"/>
        <acoustic name="L exc" value="1" surfRegion="L exc surf" volumeNeighbour="S acou"/>
<constraint type="volume" access="plain" mode="constraint" bound="upperBound" value="0.8"/>
<optimizer type="snopt" maxIterations="100"/>
<ersatzMaterial region="S opt" material="acoustic" method="simp">
    <designSpace local element cache="false"/>
        <filter neighborhood="maxEdge" value="1.6" type="density"/>
    <design name="density" initial="0.5" physical lower="1e-9" upper="1.0"/>
    <transferFunction type="simp" application="acoustic" param="1"/>
    <export save="last" write="iteration"/>
<commit mode="forward" stride="10"/>
```

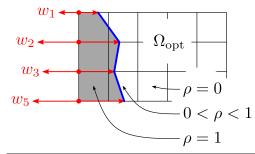
Shape Mapping XML



Shape mapping DOFs oriented in x-direction.



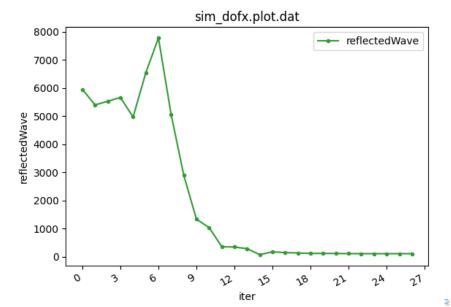
Shape mapping DOFs oriented in y-direction.



Monitoring: plotviz.py



Display the contents of the *.plot.dat file e.g to check convergence.



Monitoring: show_density.py



Display the contents of the *.density.xml file to visualize design.



Monitoring

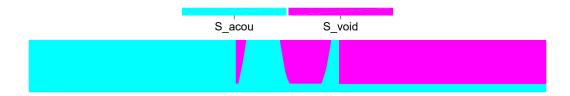
Monitoring tools can be used in parallel to the optimization process, this allows the user to spot problems early.

Post Processing: evaluate, threshhold.py



Evaluate: Instead of selecting an optimizer, evaluate can be used to solve the FEM problem with loaded pseudo densities.

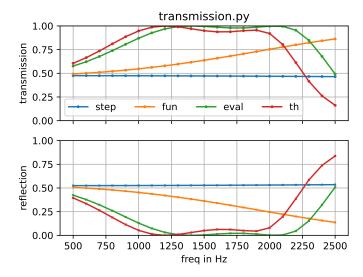
Threshhold: To ensure the elements with $0 < \rho_e < 1$ don't cause problems, threshholding is used to simulate a pure FEM model, without pseudo densities. Helper program threshhold.py (not published yet).



Post Processing: transmission.py



Transmission: Finally, we compute the transmission/reflection coefficients. Helper program transmission.py (not published yet).



Summary



Good News

Topology optimization workflow in openCFS now supports the acoustic pressure formulation for harmonic problems.

Features:

- Dynamic SIMP for acouPressure PDE
- dynamicOut and reflectedWave cost functions
- Multi frequency optimization in two formulations
- Several filter options working and tested
- Shape mapping support (not published yet)
- New post processing Python modules (not published yet)

Any Questions?